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Solitons in coupled Ablowitz–Ladik chains

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Abstract

A model of two coupled Ablowitz–Ladik (AL) lattices is introduced. While the system as a whole is not integrable, it admits reduction to the integrable AL model for symmetric states. Stability and evolution of symmetric solitons are studied in detail analytically (by means of a variational approximation) and numerically. It is found that there exists a finite interval of positive values of the coupling constant in which the symmetric soliton is stable, provided that its mass is below a threshold value. Evolution of the unstable symmetric soliton is further studied by means of direct simulations. It is found that the unstable soliton breaks up and decays into radiation, or splits into two counter-propagating asymmetric solitons, or evolves into an asymmetric pulse, depending on the coupling coefficient and the mass of the initial soliton.

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1. Introduction

Dynamics of solitary waves (that we will refer to as "solitons", without implying mathematical rigor) in nonlinear lattices is a vast field of research, which is of great interest in its own right and finds important physical applications. A majority of nonlinear discrete systems are nonintegrable. However, there are paradigm models that are integrable by means of the inverse scattering transform, most notably, the Toda lattice [1] and Ablowitz–Ladik (AL) [2] chain. A nonintegrable generalization of the latter model, in the form of its combination with the discrete nonlinear Schrödinger (NLS) equation, was also studied in detail [3,4]. Although the AL model finds fewer direct applications than its discrete-NLS counterpart, it may describe, for instance, ladder-structured lattices [5].

The availability of exact soliton solutions in integrable models makes it possible to study nontrivial dynamical effects in more complex systems that can be built on the basis of integrable ones. In particular, a challenging issue is to study solitons and their stability in two coupled systems, which are integrable in isolation. A physically important example is a dual-core optical fiber (the so-called directional coupler [6]). While each core is described by the integrable NLS equation, the coupled system is not integrable, and it gives rise to a new effect: an obvious symmetric soliton solution, with its energy equally split between the cores, becomes unstable if the energy exceeds a certain

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critical value [6]. As a result of the onset of the instability, a pair of new solitons with a broken symmetry emerge (they are mirror images to each other). Later, similar bifurcations destabilizing symmetric solitons and replacing them by asymmetric ones were found in a dual-core system with quadratic (rather than cubic) nonlinearity [7], and in a dual-core fiber with the Bragg grating [8].

A natural step is to introduce a system of two coupled AL chains and investigate the stability and nonlinear evolution of its solitons. A system of two AL chains with a coupling that does *not* admit reduction to the usual AL model was introduced in Ref. [9], and solitary waves, as well as moving breathers, were found in it. In this Letter, we focus on a system of coupled AL chains that admits reduction to the integrable AL model and seems, as a matter of fact, more natural. The system is

$$i\dot{u}_{n} + (1 + |u_{n}|^{2})[(u_{n+1} + u_{n-1}) + \varepsilon(v_{n+1} + v_{n-1})] = 0,$$
(1.1)

$$i\dot{v}_{n} + (1 + |v_{n}|^{2})[(v_{n+1} + v_{n-1}) + \varepsilon(u_{n+1} + u_{n-1})] = 0, \qquad (1.2)$$

where u_n and v_n are complex dynamical variables at the *n*th site of the chain, the overdot stands for the time derivative, and ε is a real coupling constant. Under the symmetric reduction $u_n = v_n$, Eqs. (1.1) and (1.2) reduce to the AL model proper.

Results presented in this Letter demonstrate that the system of Eqs. (1.1) and (1.2) is definitely nonintegrable, unlike the AL model. The present model conserves only two dynamical invariants, viz., the Hamiltonian,

$$H = -\sum_{n=-\infty}^{+\infty} \left[(u_n u_{n-1}^* + u_n^* u_{n-1} + v_n v_{n-1}^* + v_n^* v_{n-1}) + \varepsilon (u_n v_{n-1}^* + u_n^* v_{n-1} + u_n^* v_{n-1} + u_{n-1} v_n^* + u_{n-1}^* v_n) \right],$$
(1.3)

and the total "mass",

$$M = \sum_{n=-\infty}^{+\infty} \left[\ln(1+|u_n|^2) + \ln(1+|v_n|^2) \right]$$
(1.4)

(note that the masses corresponding to the u- and v-fields are not conserved separately).

The symmetric reduction, $u_n(t) \equiv v_n(t)$, generates a solution to Eqs. (1.1) and (1.2) which is tantamount to the well-known AL soliton,

$$u_n(t) = v_n(t) = (\sinh a) \operatorname{sech}(an + vt - \theta_0)$$
$$\times \exp\left[-i(bn + \omega t - \phi_0)\right] \tag{1.5}$$

(in this Letter, we only consider bright solitons). Here, θ_0 and ϕ_0 are position and phase constants, while parameters *a* and *b* determine the soliton's velocity and frequency,

$$v = 2(1 + \varepsilon) \sinh a \cdot \sin b,$$

$$\omega = -2(1 + \varepsilon) \cosh a \cdot \cos b \qquad (1.6)$$

(notice that the coupling parameter ε does not appear in the expression (1.5) as it is absorbed into the time variable, which amounts to a rescaling of the velocity and frequency in Eq. (1.6)). The value of the mass (1.4) corresponding to the soliton (1.5) is

$$M_{\rm sol} = 4a. \tag{1.7}$$

In this Letter, we primarily focus on the stability of symmetric solitons (1.5) with zero velocity, i.e., $b = \theta_0 = 0$.

The underlying Eqs. (1.1) and (1.2) also allow the anti-symmetric reduction, $u_n(t) \equiv -v_n(t)$. But there is no necessity to treat this case separately, as it is tantamount to the symmetric reduction with the change $\varepsilon \rightarrow -\varepsilon$. We stress that, in this Letter, we consider both positive and negative values of ε . In particular, the symmetric-soliton solution given by Eqs. (1.5) and (1.6) remains valid also in the case $1 + \varepsilon < 0$.

The rest of the Letter is organized as follows. In Section 2, we put forward an analytical approach to the stability problem, based on a variational approximation (a review of the application of this technique to solitons was recently given in Ref. [10]). This approach, which we employ in its simplest form, will produce partial information on the stability, as it will be seen from comparison with results of numerical computation of stability eigenvalues. The numerical eigenvalues are presented in Section 3. Finally, direct numerical simulations of the full system of Eqs. (1.1) and (1.2), showing nonlinear development of the instability, are displayed in Section 4.

2. The variational approximation

A feasible source of instability of the two-component soliton (1.5) is an eigenmode of small perturbations splitting the two components. To accommodate this mode, we adopt the following *ansatz* for a perturbed soliton,

$$u_n(t) = (\sinh a) \operatorname{sech} \left[a \left(n - x(t) \right) \right] \\ \times \exp \left[+ i c(t) n + i \phi(t) \right],$$
(2.1)

$$v_n(t) = (\sinh a) \operatorname{sech} \left[a \left(n + x(t) \right) \right]$$
$$\times \exp \left[-ic(t)n + i\phi(t) \right], \tag{2.2}$$

where 2x(t) is a small time-dependent separation between centers of the *u*- and *v*-components, and 2c(t)is a dynamically conjugate variable, viz., a wavenumber difference between the components, while $\phi(t)$ is a common time-dependent phase of both components. Note that this ansatz does not include another possible perturbation mode, which may introduce a phase difference between the two components of the soliton, its conjugate variable being the amplitude difference between the components [11]. We focus on the restricted ansatz (2.1), (2.2) which accounts for the position splitting, as its counterpart which also takes into consideration the phase differences turns out to be cumbersome to calculate, therefore it will not be pursued in this Letter.

To apply the variational technique, we need a Lagrangian of the coupled system (1.1), (1.2), which is

$$L = \frac{i}{2} \sum_{n=-\infty}^{+\infty} \left[\left(\dot{u}_n u_n^* - \dot{u}_n u_n^* \right) \frac{\ln(1 + |u_n|^2)}{|u_n|^2} + \left(\dot{v}_n v_n^* - \dot{v}_n^* v_n \right) \frac{\ln(1 + |v_n|^2)}{|v_n|^2} \right] - H, \quad (2.3)$$

where *H* is the Hamiltonian defined in Eq. (1.3). An *effective Lagrangian* can be calculated by substituting the ansatz (2.1), (2.2) into the Lagrangian (2.3) and expanding it in powers of the small separation parameters *x* and *c* up to quadratic terms, which are necessary to generate perturbed equations of motion linear in *x* and *c*. Due to the obvious symmetry of the Lagrangian (2.3), the time derivative of *x* will not appear in the result, while the time derivative \dot{c} of *c* may only appear linearly (being multiplied by *x*). Finally, making use of some formulas for infinite sums related

to the soliton's waveform (involving $\operatorname{sech}(an)$), which were borrowed from Ref. [4], the effective Lagrangian is found in the following form

$$L_{\text{eff}} = -4[a\dot{c}x + (\sinh a)(c^2 + Aa^2\varepsilon x^2)], \qquad (2.4)$$

where A is a positive constant defined as

$$A \equiv \sinh a \sum_{n=-\infty}^{+\infty} \left\{ \frac{1}{2} \operatorname{sech}(an) \operatorname{sech}(a(n-1)) \times \left[\operatorname{sech}^{2}(an) + \operatorname{sech}^{2}(a(n-1)) \right] + \operatorname{sech}^{2}(an) \operatorname{sech}^{2}(a(n-1)) \times \sinh(an) \sinh(a(n-1)) \right\} - 1.$$
(2.5)

In particular, A = 1 in the continuum limit $(a \rightarrow 0)$, and $A \approx 6 \exp(-2a)$ in the ultradiscrete limit $(a \rightarrow \infty)$.

The effective Lagrangian (2.4) immediately gives rise to an evolution equation

$$\ddot{x} + 4\varepsilon (\sinh^2 a) Ax = 0, \qquad (2.6)$$

which predicts that the symmetric soliton (1.5) is unstable against the splitting perturbation mode if $\varepsilon < 0$. In this case, the instability growth rate is

$$\lambda = (2\sinh a)\sqrt{-A\varepsilon},\tag{2.7}$$

as predicted by Eq. (2.6), i.e., by the variational approximation.

3. Numerical analysis of the instability of symmetric solitons

A general stability analysis of the symmetric soliton (1.5) with $v = \theta_0 = 0$ assumes that a perturbed solution is taken as

$$u_n = (U_n + \tilde{u}_n)e^{-i\omega t}, \qquad v_n = (U_n + \tilde{v}_n)e^{-i\omega t},$$

$$U_n \equiv (\sinh a)\operatorname{sech}(an), \qquad (3.1)$$

where the frequency ω is the same as defined in Eq. (1.6) (with b = 0), and \tilde{u}_n, \tilde{v}_n are infinitesimal perturbations. Numerically simulating Eqs. (1.1) and (1.2) linearized about the unperturbed soliton solution, we have found that the most unstable perturbation modes are always *anti-symmetric* ones, i.e., with $\tilde{u}_n = -\tilde{v}_n$ (which is not surprising, as the same is true

for a mode destabilizing symmetric solitons in all the previously studied continuum models of the dual-core type [6-8]). Thus, we look for eigenmodes of the form

$$\tilde{u}_n = -\tilde{v}_n = f_n \exp(\lambda t) + g_n^* \exp(\lambda^* t), \qquad (3.2)$$

where λ is a (generally complex) instability growth rate. Substituting Eqs. (3.1) and (3.2) into Eqs. (1.1) and (1.2) and linearizing these equations, one eventually arrives at an eigenvalue problem based on the equations

$$(i\lambda + \omega) f_n + (1 - \varepsilon) (1 + |U_n|^2) (f_{n+1} + f_{n-1}) + (1 + \varepsilon) U_n (U_{n+1} + U_{n-1}) (f_n + g_n) = 0, \quad (3.3)$$

$$(-i\lambda + \omega)g_n + (1 - \varepsilon)(1 + |U_n|^2)(g_{n+1} + g_{n-1}) + (1 + \varepsilon)U_n(U_{n+1} + U_{n-1})(g_n + f_n) = 0, \quad (3.4)$$

which are supplemented by the boundary conditions demanding that, for discrete eigenmodes, the fields f_n and g_n vanish at $|n| = \infty$.

The eigenvalue problem (3.3) and (3.4) was solved numerically by the shooting method. Fig. 1 presents unstable eigenvalues as a function of the coupling constant ε for three different fixed values of the soliton parameter, a = 0.8, 0.9, and 1 (see Eqs. (1.5) and (1.6)). We have checked by simulating evolution governed by the linearized equations that the unstable eigenvalues which are presented in Fig. 1 are the



Fig. 1. The numerically found unstable eigenvalue λ versus the coupling coefficient ε for the symmetric stationary soliton at different fixed values of the soliton parameter *a* (see Eqs. (1.5) and (1.6)). The solid and dashed curves show, respectively, the real and imaginary parts of λ . The imaginary part is not shown inside the stability window in the upper panel, where λ is pure imaginary. In the interval around the point $\varepsilon = -1$, the real part of λ is very small but finite in all three panels.

most unstable ones. We suspect that these are all the unstable eigenvalues in the above system (3.3) and (3.4). Even if they are not, other eigenvalues are less unstable and thus less significant.

Our numerical results for the eigenvalue problem show that, for each value of *a*, the unstable eigenmodes at $\varepsilon < 0$ are odd, i.e., $f_{-n} = -f_n$ and $g_{-n} =$ $-g_n$. When $\varepsilon > 0$, the eigenmodes are even, i.e., $f_{-n} = f_n$ and $g_{-n} = g_n$. Furthermore, when negative ε has a small absolute value, the inspection of the unstable eigenmode shows that it corresponds to a splitting of the two components (appearance of separation between their centers) in the soliton (1.5). Recall that precisely this type of the perturbation mode was assumed in the ansatz (2.1) and (2.2). On the other hand, when $\varepsilon > 0$ and small, the unstable eigenmode corresponds to a phase-difference instability, which is not accounted for by the ansatz.

As is seen in Fig. 1, in the cases a = 0.9 and 1.0 the solitons (1.5) are unstable for all values of ε . The instability may be both non-oscillatory or oscillatory (corresponding to a real or complex eigenvalue λ , respectively) in different intervals of ε . However, a stability window, $0.605 < \varepsilon < 1.654$, is found at a = 0.8. More detailed computations show that the stability window opens up at a critical value of the soliton parameter, $a_{\rm cr} \approx 0.881$, and persists in the region $a < a_{\rm cr}$. At the point $a = a_{\rm cr}$, the stability window appears (up to the accuracy of the numerical data) at the value of the coupling constant $\varepsilon_{\rm cr} = 1$.

Inspection of Fig. 1 leads to the following general conclusions. First, all symmetric solitons are unstable when $\varepsilon < 0$. In particular, near $\varepsilon = -1$, the real part of the unstable eigenvalue is very small but positive. Second, narrower solitons (with a larger mass, i.e., larger value of a) are more unstable. Third, when the soliton mass is below the threshold value $4a_{\rm cr}$, the soliton is stable inside a certain positive- ε window. These features are somewhat similar to those in the above-mentioned continuum models of the nonlinear-optical dual-core systems with the linear coupling between the cores [6-8]. In those models too, symmetric solitons become unstable if their mass exceeds a critical value, while the coupling constant is positive, and they are never stable if the coupling constant is negative. However, the stability window observed in Fig. 1 when $a < a_{cr}$ is different from stability regions in the continuum dual-core models,



Fig. 2. The instability growth rate predicted by the variational approximation, see Eq. (2.7) (the dashed curve), vs. its numerically computed counterpart (the solid curve).

as the latter stability regions have no right endpoint (they are semi-infinite).

It is natural to compare the numerically found unstable eigenvalues with the one (2.7) that was predicted by the variational approximation in the previous section. This comparison is meaningful only when $\varepsilon < 0$ and $|\varepsilon| \ll 1$, as the actual unstable mode corresponds to the variational ansatz (2.1) and (2.2) only in this case. For a = 0.8, the comparison is displayed in Fig. 2. It is not surprising that the deviation between the analytical and numerical results is large for large values of $|\varepsilon|$, when the coupling term can make the perturbed soliton strongly different from the ansatz (2.1), (2.2). For small $|\varepsilon|$, the analytical value is close to the numerical one; the remaining difference might be due to the fact that, if the two components of the soliton are separated by some distance, the symmetry of each component relative to its center is broken by the coupling term, which is not taken into regard by the ansatz.

4. Direct simulations of the instability development

In order to understand the evolution of unstable symmetric solitons, direct numerical simulations of the full nonlinear equations (1.1) and (1.2) were performed. To this end, the initial configuration was taken in the form corresponding to the ansatz (1.1),

(1.2), with an extra perturbation parameter, namely, a phase difference 2ψ between the two components of the soliton:

$$u_n(t) = (\sinh a) \operatorname{sech}(a(n - x_0))$$
$$\times \exp(-ic_0 n + i\psi_0), \tag{4.1}$$

$$v_n(t) = (\sinh a) \operatorname{sech}(a(n+x_0))$$
$$\times \exp(+ic_0 n - i\psi_0). \tag{4.2}$$

Different typical outcomes of the instability development can be illustrated by a set of contour-plot pictures pertaining to several characteristic values of ε , while all the other parameters are fixed. In Figs. 3– 7, we display the pictures for a representative case a = 0.8, $x_0 = c_0 = \psi_0 = 0.01$. In fact, exact initial values of the small perturbations are not important, while the value of the soliton parameter *a* is a significant one. In each figure, contours in the left and right panels represent the evolution of $|u_n|$ and $|v_n|$, respectively.

First of all, Fig. 3 shows that if ε belongs to the stability interval, see the upper panel in Fig. 1 (in Fig. 3, $\varepsilon = 1$), the initial perturbation indeed does not trigger any instability. Next, Fig. 4 shows that, in the case $\varepsilon = -7$, which corresponds to strong instability, the soliton gets completely destroyed, decaying into radiation. Decreasing the absolute value of negative ε , i.e., proceeding to weaker instability, according to Fig. 1, we observed a trend of splitting of the original



Fig. 3. Evolution of the initially perturbed symmetric soliton in the case a = 0.8, $\varepsilon = 1$, when the soliton is stable. In this figure and below, all contours start at the level 0.05 and increase with an increment of 0.2.



Fig. 4. Evolution of an unstable symmetric soliton in the case a = 0.8, $\varepsilon = -7$.



Fig. 5. Splitting of an unstable symmetric soliton in the case a = 0.8, $\varepsilon = -0.08$.



Fig. 6. Conversion of an unstable symmetric soliton into a stable asymmetric one in the case a = 0.8, $\varepsilon = 0.3$.



Fig. 7. Evolution of an unstable soliton in the case a = 0.8, $\varepsilon = 2$.

unstable symmetric soliton into two *moving* ones, each being a two-component pulse. An example of that is shown in Fig. 5 for $\varepsilon = -0.08$. It is noteworthy that the symmetry of each secondary soliton is strongly broken (the amplitude of one component is definitely larger than that of the other), but they are (at least, approximately) mirror images to each other, so that the global symmetry is conserved.

In the case when the symmetric soliton is unstable at positive ε , the character of the instability is quite different from that described above for $\varepsilon < 0$. In this case, the instability is non-oscillatory. In Fig. 6, which pertains to $\varepsilon = 0.3$, a noteworthy result is the formation of a soliton with a strongly broken symmetry and (nearly) periodic internal oscillations, which is accompanied by emission of small amounts of radiation. This instability-induced spontaneous symmetry breaking resembles what is known in the above-mentioned continuum models of the dual-core type [6–8]. Of course, in all the cases when spontaneous symmetry breaking is observed, its sign (e.g., the difference between the left and right panels in Fig. 6) is determined by a random initial perturbation.

Finally, Fig. 7 shows the situation in the case $\varepsilon = 2$, which lies beyond the right border of the stability interval in Fig. 1 (recall that no such border occurs in the continuum dual-core models). As is seen, in this case the instability also breaks the symmetry of the soliton (in the beginning). However, an unusual feature here is that the centers of both components oscillate, essentially, in-phase. Unlike what was seen in all the other figures, spontaneous onset of such in-phase oscillations seems to violate the momentum conservation; however, one should keep in mind that lattice systems conserve no momentum, in view of the lack of the continuous translational invariance in them. Nevertheless, the appearance of such a dynamical state is a remarkable fact which may deserve further investigation.

5. Conclusion

In this Letter, we have introduced a model of two coupled Ablowitz–Ladik chains. While the system as a whole is not integrable, it admits reduction to the integrable AL model for symmetric states. We have studied the stability and nonlinear evolution of stationary symmetric solitons in detail. Both the analytical consideration, based on the variational approximation, and numerical computation of the instability eigenvalues have demonstrated that the soliton may be unstable. Numerical results also show that, provided that the soliton's mass is below a critical value, there exists a finite interval of positive values of the coupling constant ε in which the symmetric soliton is stable. Comparison of the approximate analytical and exact numerical unstable eigenvalues shows that the agreement is reasonable for small negative values of the coupling constant. Evolution of the unstable symmetric soliton was further studied by means of direct simulations. It was found that the unstable soliton can decay into radiation, or split in two counter-propagating asymmetric solitons, or evolve into an asymmetric pulse, depending on the values of the coupling coefficient ε and the soliton mass.

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