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Analytical construction of soliton families in one- and two-dimensional nonlinear Schrödinger equations with nonparity-time-symmetric complex potentials

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Abstract

The existence of soliton families in nonparity-timesymmetric complex potentials remains poorly understood, especially in two spatial dimensions. In this article, we analytically investigate the bifurcation of soliton families from linear modes in one- and two-dimensional nonlinear Schrödinger equations with localized Wadatitype nonparity-time-symmetric complex potentials. By utilizing the conservation law of the underlying non-Hamiltonian wave system, we convert the complex soliton equation into a new real system. For this new real system, we perturbatively construct a continuous family of low-amplitude solitons bifurcating from a linear eigenmode to all orders of the small soliton amplitude. Hence, the emergence of soliton families in these nonparity-time-symmetric complex potentials is analytically explained. We also compare these analytically constructed soliton solutions with high-accuracy numerical solutions in both one and two dimensions, and the asymptotic accuracy of these perturbation solutions is confirmed.

KEYWORDS

bifurcation, nonparity-time-symmetric potential, soliton family

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1 | INTRODUCTION

Nonlinear wave phenomena in parity-time (\mathcal{PT}) symmetric systems have been under intensive studies in the past decade (see Refs.1–3 for reviews). Although the concept of \mathcal{PT} symmetry originated from non-Hermitian quantum mechanics,^{4–6} it was the interpretation of \mathcal{PT} symmetry as balanced gain and loss that made it flourish in optics and many other branches of physics.^{1–3,6,7} \mathcal{PT} symmetric systems are important for at least two reasons. From the intellectual point of view, these systems are the first reported non-Hamiltonian systems that, despite the gain and loss, exhibit many properties of Hamiltonian systems—such as all-real linear spectra and continuous families of solitons.^{1–6} From the practical point of view, \mathcal{PT} symmetry has inspired many interesting applications, such as the coherent perfect absorber laser^{8–10} and single-mode \mathcal{PT} lasers.^{11,12} While applications of \mathcal{PT} symmetry are still developing, its peculiar Hamiltonian-like phenomena, such as the existence of all-real spectrum and continuous families of solitons, have already been understood from a mathematical point of view.^{1,2,5,6} In particular, this understanding relies entirely on the \mathcal{PT} symmetry.

In the past few years, it was discovered that certain non- \mathcal{PT} -symmetric non-Hamiltonian systems also share properties of Hamiltonian systems. For example, the linear Schrödinger operator with certain types of non- \mathcal{PT} -symmetric complex potentials could still admit all-real spectra.^{13–16} In addition, the one- and two-dimensional nonlinear Schrödinger (NLS) equations with Wadati-type non- \mathcal{PT} -symmetric complex potentials could still admit continuous families of solitons.^{15,17–19} Furthermore, in the NLS equations with Wadati-type non- \mathcal{PT} -symmetric potentials, the linear-stability spectra of solitons still exhibit the quartet eigenvalue symmetry that is typical of Hamiltonian systems.²⁰ In a generic non- \mathcal{PT} -symmetric non-Hamiltonian system, none of these properties would hold. Thus, why these Hamiltonian-like properties arise in certain types of non- \mathcal{PT} -symmetric non-Hamiltonian systems is an intriguing theoretical question. While the all-real spectra of certain non- \mathcal{PT} -symmetric complex potentials can be explained by techniques such as supersymmetry and pseudo-Hermiticity,^{13–16} analytical explanations for the other properties associated with nonlinear non- \mathcal{PT} -symmetric systems remain elusive.

This article is concerned with the question of why the NLS equations with Wadati-type non- \mathcal{PT} -symmetric complex potentials could still admit continuous families of solitons. This phenomenon is peculiar, because these non- \mathcal{PT} -symmetric systems are non-Hamiltonian due to the presence of gain and loss, and solitons in non-Hamiltonian systems are generically isolated and do not exist as continuous families due to the double balancing requirement of nonlinearity with dispersion and gain with loss.²¹ Numerical evidence to support this generic behavior in a non- \mathcal{PT} -symmetric system can be found in Ref. 22, and a more mathematical reason for it can be found in Ref. 23. In view of this generic behavior and in the absence of \mathcal{PT} symmetry, why soliton families could appear in the NLS equations with special Wadati-type non- \mathcal{PT} -symmetric potentials where the spatial gain and loss distributions must be balanced in an exact anti-symmetric way, the Wadati potentials allow the gain and loss distributions to be arbitrary, which could potentially accommodate more realistic non-Hamiltonian physical systems in optics and beyond. A physical setup to realize Wadati potentials in a coherent atomic system has been proposed in Ref. 24.

In the one-dimensional (1D) case, some analytical understanding on this question has been provided in Refs. 17 and 19. In Ref. 17, Konotop and Zezyulin discovered a constant of motion for the underlying soliton equation with Wadati potentials. Combining this constant of motion with a shooting argument, the authors gave a plausible, but not definitive, explanation for these soliton

families. In Ref. 19, the authors used this constant of motion to convert the original second-order complex soliton equation into a second-order real equation for the amplitude of the soliton. From this real soliton-amplitude equation, it was shown that continuous families of solitons bifurcating from linear modes could be constructed perturbatively. One drawback of this treatment in Ref. 19 is that this real amplitude equation has some sign ambiguity in front of a square root term, which can cause technical complications. Another drawback, which is more serious, is that this treatment cannot be generalized to two and higher spatial dimensions.

In the 2D case, while soliton families in the 2D NLS equations with separable Wadati-type non- \mathcal{PT} -symmetric potentials were briefly mentioned on numerical grounds in Ref. 18, there has been absolutely no analytical explanation for this phenomenon yet, except that a conservation law for the underlying non-Hamiltonian 2D equation was reported in that same article. Note that in this 2D case, the shooting argument of Ref. 17 no longer applies. In addition, the real-amplitude-equation treatment of Ref. 19 also fails. Thus, new approaches need to be developed to analytically explain these 2D soliton families.

We would like to mention that continuous families of solitons in the 1D NLS equation perturbed by non- \mathcal{PT} -symmetric potentials more general than the Wadati-type were also reported by Kominis et al.²⁵ through Melnikov's perturbation method. As the authors' analysis was carried out only to the first order of the perturbation series, we suspect that those soliton families in non-Wadati potentials are valid only to the first order of the perturbation theory, but not to higher orders. If so, then those "soliton families" would be just approximate solutions, but not true solitons. This suspicion makes it more imperative to analytically explain the existence of soliton families in non- \mathcal{PT} -symmetric Wadati potentials, since such analytical understanding could shed light on the nature of "soliton families" reported in Ref. 25 for non-Wadati potentials.

In this article, we analytically investigate the bifurcation of soliton families from linear modes in the 1D and 2D NLS equations with non- \mathcal{PT} -symmetric Wadati-type localized potentials through a new perturbative treatment. Utilizing the constant of motion of the underlying soliton equation, we convert this complex soliton equation into a new real system. The advantage of this new real system is that it allows us to analytically construct low-amplitude soliton families perturbatively to all orders of the amplitude in both one and two dimensions. Hence, soliton families in these 1D and 2D non- \mathcal{PT} -symmetric systems are analytically established. The reason this construction can be pursued to all orders is that the linear operator of these perturbation equations possesses two localized functions in its kernel, whereas the associated adjoint operator contains a single localized or bounded function in its kernel. These kernel structures, together with the phase invariance of solitons, ensure that at each order, the Fredholm condition for localized perturbation solutions can always be satisfied. Hence, we can construct a low-amplitude soliton solution, as a perturbation series to all orders, at each propagation constant in a continuous interval bordering the linear eigenmode of the potential. In other words, a soliton family bifurcating from a linear mode is derived in the underlying non- \mathcal{PT} -symmetric non-Hamiltonian system. These analytically constructed perturbation-series solutions for the soliton families are also compared to direct numerical solutions, and the asymptotic accuracy of these perturbation series solutions is confirmed.

2 CONSTRUCTION OF SOLITON FAMILIES IN THE 1D CASE

We first consider the 1D NLS equation

$$iU_t + U_{xx} + V(x)U + \sigma |U|^2 U = 0$$
(1)

with a non- \mathcal{PT} -symmetric Wadati potential

$$V(x) = g^2(x) + ig'(x),$$
 (2)

where g(x) is an asymmetric real function that is differentiable everywhere, the prime represents differentiation, and $\sigma = \pm 1$ is the sign of cubic nonlinearity. As g(x) is real and asymmetric, $V^*(-x) \neq V(x)$, that is, the complex potential V(x) is non- \mathcal{PT} -symmetric.^{1–3,7} Potentials of this form appeared in Wadati's investigation of complex potentials with real spectra,²⁶ and are thus sometimes referred to as the Wadati potentials in the literature. In the optical context, the complex potential V(x) in Equation (1) corresponds to the complex refractive index of the medium, where the imaginary part of V(x), that is, Im(V), describes the spatial gain and loss distributions, with regions of Im(V) > 0 being lossy and regions of Im(V) < 0 being gain.^{1–3,7} In this physical setting, since the function g(x) in the Wadati potential (2) can be arbitrary, this complex potential then can accommodate optical systems with arbitrary gain and loss distributions. The main constraint of the Wadati potential is that, the real refractive index profile of the medium, as described by the real part of the complex potential Re(V), should be designed accordingly as $g^2(x)$. But this requirement on the real refractive index profile can be readily met given the sophisticated refractive-index engineering technology that is currently widely available.

An important property of the NLS equation (1) with Wadati potentials is that although this equation is non-Hamiltonian due to the complex potential, it admits a conservation law

$$Q_t + J_x = 0, (3)$$

where

$$Q = -U^*(iU_x - gU), \quad J = |U_x + igU|^2 + iU^*U_t + \frac{o}{2}|U|^4, \tag{4}$$

and the asterisk "*" represents complex conjugation. This conservation law is a special case of the more general conservation law reported in Ref. 18 for the 2D NLS equation with a separable Wadati-type potential.

Solitons in Equation (1) are of the form

$$U(x,t) = e^{i\mu t}u(x),$$
(5)

where μ is a real propagation constant, and u(x) is a localized function satisfying the soliton equation

$$u_{xx} + (g^2 + ig')u - \mu u + \sigma |u|^2 u = 0.$$
 (6)

Notice that this complex soliton equation is phase-invariant, that is, if u(x) is a solution, so is $e^{i\theta}u(x)$, where θ is an arbitrary real constant. Substituting the soliton solution (5) into the conservation law (3), we get dJ/dx = 0, where

$$J(x) = |u_x + igu|^2 - \mu |u|^2 + \frac{\sigma}{2} |u|^4.$$
 (7)

As solitons decay to zero as $x \to \pm \infty$, we see that J(x) = 0, which is a constant of motion for the soliton equation (6). This constant of motion is equivalent to the one reported in Ref. 17 for the same equation (6).

Soliton families in Equation (6), parameterized by the propagation constant μ , for non- \mathcal{PT} symmetric Wadati potentials were reported numerically in Ref. 15, and studied analytically in Refs. 17, 19, and 23 with limited success. In particular, the perturbative construction of smallamplitude soliton families as proposed in Refs. 23 and 19 exhibits some difficulties. The perturbative construction in Ref. 23 was based on the complex soliton equation (6). The difficulty with this construction, as explained in Ref. 23, is that each order of the perturbation series creates a nontrivial condition that needs to be satisfied, and it is almost impossible to prove that all those infinite number of conditions would hold. The perturbative construction in Ref. 19 was based on a real second-order equation for the amplitude |u(x)| of the soliton, and this real amplitude equation was derived from the original complex equation (6) with the help of the above constant of motion J(x) = 0. This latter construction removed those infinite number of nontrivial conditions of the former, and thus made the perturbative construction possible, at least in principle. But it does create some technical difficulties. For example, this reduced amplitude equation contains a square root term, whose sign can be ambiguous and cause technical complications. To remove this ambiguity, some technical assumptions had to be imposed in Ref. 19. A more serious problem with this latter treatment is that it does not work for the 2D case. In other words, in two (and higher) spatial dimensions, we will not be able to convert the original complex soliton equation into a single real equation for the amplitude of the soliton.

In this section, we will develop a new perturbative construction of low-amplitude soliton families in Equation (6), which can be easily pursued to all orders of the perturbation series. More importantly, this new 1D treatment can be readily generalized to the 2D case.

For the technical convenience of our perturbative construction, we will assume that the Wadati potential (2) is localized in space, that is, the real function g(x) and its derivative g'(x) in this potential will be assumed to be localized. This assumption of locality on the potential has two main benefits. One is that such a Wadati potential often admits a discrete real eigenvalue,^{15,16} which is the starting point of our perturbative calculation. The other is that under this locality assumption, the eigenfunction associated with this discrete real eigenvalue of the potential features simple and explicit exponential decay at large distances. These explicit decay rates of the eigenfunction facilitate our derivation and understanding of the kernels for the linearization operator and its adjoint in the upcoming Section 2.2. If the Wadati potential (2) is not localized (for instance, unbounded) but still admits a discrete real eigenvalue, then the analysis of this section can still go through, because the kernel structures of the linearization operator and its adjoint to be established in Section 2.2 would still remain valid. However, if the Wadati potential (2) is periodic, then the situation would be different. In this case, the periodic potential does not admit any discrete real eigenvalues. Instead, the spectrum of the potential comprises Bloch bands. Low-amplitude solitons, if any, would have to bifurcate out from edges of these Bloch bands as envelope solitons.²⁷ The analytical calculation of soliton bifurcation from Bloch-band edges in a periodic Wadati potential would be very different from the one to be developed in this section, and it will be left for future studies.

2.1 | A new real system for solitons and its perturbation expansion

It can be checked that the original complex soliton equation (6) is equivalent to two real equations—one is that the real part of (6) is zero, and the other is J = 0, where J is given in

Equation (7). The first real equation comes directly from (6), and the second one is the constant of motion discussed below Equation (7). To see these two real equations combined could also reproduce the original complex equation (6), we only need to notice that dJ/dx is equal to the real part of the product between $u_x^* - igu^*$ and the left side of the complex soliton equation (6). Thus, if J = 0 and the real part of (6) is zero, then the imaginary part of (6) needs to be zero as well.

Expressing u(x) as

$$u(x) = p(x) + iq(x), \tag{8}$$

where p(x) and q(x) are the real and imaginary parts of the complex function u(x), these two real equations for solitons are

$$p_{xx} + (g^2 - \mu)p - g'q + \sigma(p^2 + q^2)p = 0,$$
(9)

$$(p_x - gq)^2 + (q_x + gp)^2 - \mu(p^2 + q^2) + \frac{\sigma}{2}(p^2 + q^2)^2 = 0.$$
(10)

This system of two real equations will be the one we use to analytically calculate soliton families. It is important to notice that this is a third-order real system, which contrasts the original soliton equation (6), which is a fourth-order real system when that complex equation is split into two real second-order equations for p(x) and q(x). This third-order real system also contrasts the second-order real system we derived in Ref. 19 for the amplitude |u(x)| of the soliton.

Now, we perturbatively construct a continuous family of low-amplitude solitons bifurcating from a linear discrete eigenmode of a localized Wadati potential. Suppose the Schrödinger operator $\partial_{xx} + V(x)$ with a localized Wadati potential (2) admits a discrete real eigenvalue μ_0 , whose eigenfunction is $\phi(x) + i\psi(x)$, where $\phi(x)$ and $\psi(x)$ are localized real functions. Then,

$$\left(\partial_{xx} + g^2 + ig'\right)(\phi + i\psi) = \mu_0(\phi + i\psi). \tag{11}$$

The existence of such a real eigenvalue is common in a Wadati potential. For instance, it was shown in Ref. 15 that if g(x) is a single-humped localized real function, then the spectrum of the corresponding Wadati potential is strictly real. In the more general case, it was shown in Ref. 16 that eigenvalues in a Wadati potential always come as complex-conjugate pairs and are thus often real. Because this potential is assumed to be localized, its discrete real eigenvalue μ_0 must be positive, that is, $\mu_0 > 0$.

Bifurcating from this linear discrete eigenmode, we seek a low-amplitude soliton at each real propagation constant μ near μ_0 , and this soliton can be expanded into the following perturbation series:

$$p(x;\mu) = \epsilon^{1/2} \left[p_0(x) + \epsilon p_1(x) + \epsilon^2 p_2(x) + \cdots \right], \tag{12}$$

$$q(x;\mu) = \epsilon^{1/2} [q_0(x) + \epsilon q_1(x) + \epsilon^2 q_2(x) + \cdots],$$
(13)

where $\epsilon = \mu - \mu_0$ and is assumed to be small positive (so that $\epsilon^{1/2}$ is real). This means that we assume that the bifurcation is to the right side of μ_0 , that is, $\mu > \mu_0$. As we will see in later text (see Equation (34)), this rightward bifurcation can be induced by a proper choice on the sign of nonlinearity σ . If this sign of nonlinearity is opposite of that choice, the soliton bifurcation will be to the left side of μ_0 . In that case, we can define $\epsilon = \mu_0 - \mu$, and the rest of the perturbative calculation would be very similar.

Substituting the above perturbation expansion into the real system (9)–(10), we get a sequence of real equations for the functions (p_k, q_k) . The equations for (p_0, q_0) are

$$(\partial_{xx} + g^2 - \mu_0)p_0 - g'q_0 = 0, \tag{14}$$

$$(p_{0x} - gq_0)^2 + (q_{0x} + gp_0)^2 - \mu_0(p_0^2 + q_0^2) = 0.$$
⁽¹⁵⁾

Even though this is a nonlinear system, it is scaling invariant, that is, if (p_0, q_0) is a solution, so is $(\alpha p_0, \alpha q_0)$, where α is an arbitrary real constant. Thus, this system is actually an eigenvalue problem in disguise and is equivalent to the linear complex eigenvalue problem (11). Its solution then is

$$\begin{bmatrix} p_0 \\ q_0 \end{bmatrix} = c_0 \begin{bmatrix} \phi \\ \psi \end{bmatrix},\tag{16}$$

where c_0 is a real constant to be determined. Indeed, since $\phi + i\psi$ is a solution to the linear eigenvalue problem (11), the above (p_0, q_0) then satisfy the original equations (9)–(10) to leading order, which are Equations (14) and (15).

Utilizing the above (p_0, q_0) solution, we find that the functions (p_k, q_k) for $k \ge 1$ are governed by the following linear nonhomogeneous system of equations

$$\mathcal{L}\begin{bmatrix} p_k\\ q_k \end{bmatrix} = \begin{bmatrix} f_k\\ g_k \end{bmatrix},\tag{17}$$

where

$$\mathcal{L} = \begin{bmatrix} \partial_{xx} + g^2 - \mu_0 & -g' \\ (\phi' - g\psi)\partial_x + g(\psi' + g\phi) - \mu_0\phi & (\psi' + g\phi)\partial_x - g(\phi' - g\psi) - \mu_0\psi \end{bmatrix},$$
(18)

$$\begin{bmatrix} f_1 \\ g_1 \end{bmatrix} = c_0 \begin{bmatrix} \phi - \sigma c_0^2 (\phi^2 + \psi^2) \phi \\ \frac{1}{2} (\phi^2 + \psi^2) - \frac{1}{4} \sigma c_0^2 (\phi^2 + \psi^2)^2 \end{bmatrix},$$
(19)

$$\begin{bmatrix} f_2 \\ g_2 \end{bmatrix} = \begin{bmatrix} (1 - 3\sigma p_0^2 - \sigma q_0^2) p_1 - 2\sigma p_0 q_0 q_1 \\ \frac{1}{2c_0} [2(1 - \sigma p_0^2 - \sigma q_0^2) (p_0 p_1 + q_0 q_1) + \mu_0 (p_1^2 + q_1^2) - (p_{1x} - gq_1)^2 - (q_{1x} + gp_1)^2)] \end{bmatrix},$$
(20)

$$\begin{bmatrix} f_k \\ g_k \end{bmatrix} = \begin{bmatrix} \mathcal{M}_{11} & \mathcal{M}_{12} \\ \mathcal{M}_{21} & \mathcal{M}_{22} \end{bmatrix} \begin{bmatrix} p_{k-1} \\ q_{k-1} \end{bmatrix} + \begin{bmatrix} \mathcal{N}_k^{[1]} \\ \mathcal{N}_k^{[2]} \\ \end{bmatrix}, \quad k \ge 3,$$
(21)

the matrix elements \mathcal{M}_{ij} are k-independent and given by the formulae

$$\begin{split} \mathcal{M}_{11} &= 1 - 3\sigma p_0^2 - \sigma q_0^2, \\ \mathcal{M}_{12} &= -2\sigma p_0 q_0, \\ \mathcal{M}_{21} &= \frac{1}{c_0} \left[p_0 \left(1 - \sigma p_0^2 - \sigma q_0^2 \right) + \mu_0 p_1 - (p_{1x} - gq_1) \partial_x - g(q_{1x} + gp_1) \right], \\ \mathcal{M}_{22} &= \frac{1}{c_0} \left[q_0 \left(1 - \sigma p_0^2 - \sigma q_0^2 \right) + \mu_0 q_1 + g(p_{1x} - gq_1) - (q_{1x} + gp_1) \partial_x \right], \end{split}$$

and $\mathcal{N}_k^{[1]}$, $\mathcal{N}_k^{[2]}$ are functions that depend only on k, p_0 , p_1 , ..., p_{k-2} , q_0 , q_1 , ..., q_{k-2} and g(x). For example, when k = 3,

$$\begin{split} \mathcal{N}_{3}^{[1]} &= -\sigma \big(3p_{0}p_{1}^{2} + 2p_{1}q_{0}q_{1} + p_{0}q_{1}^{2} \big), \\ \mathcal{N}_{3}^{[2]} &= \frac{1}{2c_{0}} \big[\big(p_{1}^{2} + q_{1}^{2}\big) \left(1 - \sigma p_{0}^{2} - \sigma q_{0}^{2} \right) - 2\sigma (p_{0}p_{1} + q_{0}q_{1})^{2} \big]. \end{split}$$

Next, we will show that we can solve the linear nonhomogeneous equations (17) and obtain localized solutions (p_k , q_k) for all k, using the Fredholm alternative method.

2.2 | Kernel structures of the linear operator and its adjoint operator

The key to solving linear nonhomogeneous equations (17) by the Fredholm alternative method is to understand the kernel structures of the linear operator \mathcal{L} and its adjoint operator \mathcal{L}^A . Under the inner product of

$$\langle F, G \rangle \equiv \int_{-\infty}^{\infty} [F(x)]^T \quad G(x) \quad \mathrm{d}x,$$
 (22)

where the superscript "T" represents the transpose of a vector or matrix, the adjoint operator of \mathcal{L} is

$$\mathcal{L}^{A} = \begin{bmatrix} \partial_{xx} + g^{2} - \mu_{0} & -\partial_{x}(\phi' - g\psi) + g(\psi' + g\phi) - \mu_{0}\phi \\ -g' & -\partial_{x}(\psi' + g\phi) - g(\phi' - g\psi) - \mu_{0}\psi \end{bmatrix}.$$
(23)

First, we consider the kernel structure of operator \mathcal{L} . It is easy to check that this kernel contains the following two localized functions:

$$K_1 \equiv \begin{bmatrix} \phi \\ \psi \end{bmatrix}, \quad K_2 \equiv \begin{bmatrix} -\psi \\ \phi \end{bmatrix},$$
 (24)

where

$$\mathcal{L}K_1 = \mathcal{L}K_2 = 0. \tag{25}$$

Indeed, $\mathcal{L}K_1 = 0$ is equivalent to the complex linear eigenvalue equation (11), and $\mathcal{L}K_2 = 0$ is equivalent to this complex eigenvalue equation with the eigenfunction changing from $\phi + i\psi$ to $i(\phi + i\psi)$, which clearly remains an eigenfunction. Another way to understand these kernel functions is that the first kernel function K_1 is induced by the scaling invariance of the complex linear eigenvalue equation (11), and the second kernel function K_2 is induced by the phase invariance of that same equation.

It is clear that \mathcal{L} is a third-order differential operator. Thus, the system $\mathcal{L}K = 0$ admits one more linearly independent solution K_3 in addition to K_1 and K_2 . This third solution is obviously unbounded in space. Indeed, since $\phi + i\psi$ is the eigenfunction of the Schrödinger operator with a localized potential at the positive eigenvalue μ_0 (see Equation (11)), both $\phi(x)$ and $\psi(x)$ decay exponentially at the rate of $e^{-\sqrt{\mu_0}|x|}$ when $x \to \pm \infty$. Then, converting the system $\mathcal{L}K = 0$ into a system of three first-order equations and using Abel's formula, we can show that this third solution $K_3(x)$ grows exponentially at the rate of $e^{\sqrt{\mu_0}|x|}$ when $x \to \pm \infty$.

Next, we consider the kernel structure of \mathcal{L}^A . Functions in this kernel can be derived from the functions in the kernel of \mathcal{L} . One way to do so is to first rewrite the equation $\mathcal{L}K = 0$ with $K \equiv [K^{[1]}, K^{[2]}]^T$ as a first-order system

$$\partial_x Y = P(x)Y \tag{26}$$

for $Y = [K^{[1]}, K_x^{[1]}, K^{[2]}]^T$, where P(x) is a 3 × 3 real matrix function. The fundamental matrix $\mathcal{Y}(x)$ of this first-order homogeneous system is given through the three solutions K_1, K_2 , and K_3 of the original system $\mathcal{L}K = 0$ as

$$\mathcal{Y} = \begin{bmatrix} K_1^{[1]} & K_2^{[1]} & K_3^{[1]} \\ K_{1,x}^{[1]} & K_{2,x}^{[1]} & K_{3,x}^{[1]} \\ K_{1,x}^{[2]} & K_2^{[2]} & K_3^{[2]} \end{bmatrix}.$$
(27)

The adjoint of the first-order system (26) is

$$-\partial_x Y^A = P^T Y^A,\tag{28}$$

whose fundamental matrix is $\mathcal{Y}^A = (\mathcal{Y}^{-1})^T$. Using the large-*x* asymptotics of the (K_1, K_2, K_3) solutions described in the previous paragraph, together with their Wronskian expression from Abel's formula, we can readily show that the third column of \mathcal{Y}^A is localized with its second component decaying at the rate of $e^{-\sqrt{\mu_0}|x|}$ at large |x|, whereas the first and second columns of \mathcal{Y}^A are unbounded with their second components growing at the rate of $e^{\sqrt{\mu_0}|x|}$ at large |x|.

The adjoint first-order system (28) has a simple connection with the original adjoint system $\mathcal{L}^A K^A = 0$. Specifically, if $Y^A = [Y^{A[1]}, Y^{A[2]}, Y^{A[3]}]^T$, then $K^A = [Y^{A[2]}, Y^{A[3]}/(\psi' + g\phi)]^T$. Using this connection, we see that the kernel of \mathcal{L}^A contains a single localized function, which

we denote as

$$K_0^A = \begin{bmatrix} \phi^A \\ \psi^A \end{bmatrix},\tag{29}$$

where $\mathcal{L}^A K_0^A = 0$. This K_0^A is obtained from the third column of \mathcal{Y}^A ; so $\phi^A(x)$ decays at the rate of $e^{-\sqrt{\mu_0}|x|}$ when $x \to \pm \infty$. Regarding the decay rate of $\psi^A(x)$, using dominant balance on the second equation of the adjoint system $\mathcal{L}^A K^A = 0$, we can show that $\psi^A(x)$ decays at the same rate of g(x) for large |x|. The other two functions in the kernel of \mathcal{L}^A are obtained from the first and second columns of \mathcal{Y}^A and are thus both unbounded. More specifically, their first components grow at the rate of $e^{\sqrt{\mu_0}|x|}$, when $x \to \pm \infty$.

2.3 | The Fredholm solvability condition

Utilizing the above kernel structures of operators \mathcal{L} and \mathcal{L}^A , we can solve the linear nonhomogeneous equations (17) and obtain a localized solution (p_k, q_k) for all k. To do so, we will use the Fredholm solvability condition, which will be explained in this subsection.

First, we notice that f_k on the right side of the nonhomogeneous equations (17) is localized, and its decay rate at large |x| is $e^{-\sqrt{\mu_0}|x|}$, multiplied by a certain polynomial function of x. In addition, g_k on the right side of these equations is also localized, and its decay rate at large |x| is $e^{-2\sqrt{\mu_0}|x|}$, multiplied by another polynomial function of x. The reason for these decay rates of (f_k, g_k) is that p_n and q_n in the expressions of f_k and g_k decay at the rate of $e^{-\sqrt{\mu_0}|x|}$, multiplied by a polynomial function of x. These decay rates of (p_n, q_n) can be seen from the ϵ expansions (12)–(13) of solitons (p, q), which decay at the rate of $e^{-\sqrt{\mu_0}+\epsilon|x|}$ at large |x|. These decay rates of (p_n, q_n) can also be seen from Equations (17) that determine them.

In view of the decay rates of (f_k, g_k) on the right side of the linear nonhomogeneous equations (17), as well as the kernel structures of linear operators \mathcal{L} and \mathcal{L}^A delineated in the previous subsection, the Fredholm alternative theorem says that these nonhomogeneous equations (17) would admit a localized solution (p_k, q_k) if and only if the nonhomogeneous term $(f_k, g_k)^T$ is orthogonal to the localized function K_0^A in the kernel of \mathcal{L}^A , that is,

$$\left\langle \begin{bmatrix} \phi^A \\ \psi^A \end{bmatrix}, \begin{bmatrix} f_k \\ g_k \end{bmatrix} \right\rangle = \int_{-\infty}^{\infty} \left(\phi^A f_k + \psi^A g_k \right) \mathrm{d}x = 0.$$
(30)

The Fredholm alternative theorem was originally developed for compact operators (Ref. 28, page 160), which is restrictive. But this theorem can be generalized to operators with closed range (Ref. 28, page 46). In this article, we will not attempt to prove that our operator \mathcal{L} has closed range. Instead, we will provide an elementary proof of this Fredholm alternative result below.

The necessity of the above condition (30) for Equation (17) to admit a localized solution can be derived quickly by taking the inner product of this equation with the localized function K_0^A in the kernel of \mathcal{L}^A . To prove the sufficiency of this condition, we can first rewrite Equation (17) as a first-order system

$$\partial_x Y - P(x)Y = F,\tag{31}$$

where $Y = [p_k, p_{k,x}, q_k]^T$, $F = [0, f_k, g_k/(\psi' + g\phi)]^T$, and P(x) is the 3 × 3 real matrix function in Equation (26). The fundamental matrix \mathcal{Y} for the first-order homogeneous system of (31) has been discussed before. Using this fundamental matrix and variation of parameters, we can derive the general solution to the nonhomogeneous system (31) as

$$Y(x) = \mathcal{Y}(x) \left(\mathbf{c} + \int_0^x \left[\mathcal{Y}^A(z) \right]^T F(z) dz \right), \tag{32}$$

where **c** is a constant vector, and $\mathcal{Y}^A = (\mathcal{Y}^{-1})^T$ is the fundamental matrix of the first-order adjoint system (28). In view of this explicit solution formula for Equation (31), as well as the large-*x* asymptotics of fundamental matrices \mathcal{Y} and \mathcal{Y}^A described earlier, we can readily see that a localized solution Y(x) can be obtained, through a proper choice of the third element of the **c** constant, if the following condition is met:

$$\int_{-\infty}^{\infty} \left[\mathcal{Y}_3^A(x) \right]^T F(x) \, \mathrm{d}x = 0, \tag{33}$$

where \mathcal{Y}_3^A is the third column of \mathcal{Y}^A . This third column is connected to the localized function K_0^A through a relation explained in the last paragraph of the previous subsection. Then, using the expression of *F* given above, the above condition (33) reduces exactly to the Fredholm solvability condition (30). Thus, the sufficiency of this Fredholm condition to guarantee the existence of a localized solution in Equation (17) is directly proved.

2.4 Construction of perturbation series to all orders

Now, we use the Fredholm solvability condition (30) to determine a soliton solution $u(x; \mu)$ through the perturbation series (12)–(13), to all orders of $\epsilon \equiv \mu - \mu_0$, at each μ value near μ_0 . These solutions then constitute a continuous family of solitons, parameterized by the propagation constant μ , in the non- \mathcal{PT} -symmetric Wadati potential (2).

We first consider Equation (17) for (p_1, q_1) . Substituting the (f_1, g_1) expressions (19) into the Fredholm solvability condition (30) and simplifying, we see that Equation (17) admits a localized solution (p_1, q_1) if and only if the constant c_0 is selected as

$$c_{0} = \pm \sqrt{\frac{\int_{-\infty}^{\infty} \left[\phi \phi^{A} + \frac{1}{2}(\phi^{2} + \psi^{2})\psi^{A}\right] \mathrm{d}x}{\sigma \int_{-\infty}^{\infty} \left[(\phi^{2} + \psi^{2})\phi \phi^{A} + \frac{1}{4}(\phi^{2} + \psi^{2})^{2}\psi^{A}\right] \mathrm{d}x}}.$$
(34)

In order for the quantity under the square root above to be positive, σ must have the same sign as the ratio of the two integrals in the above formula. In other words, in order for the soliton bifurcation to appear for $\mu > \mu_0$, the nonlinearity must be of a certain sign. In this case, c_0 has two value choices that differ by a sign. But it is easy to see that these two sign choices in *c* would simply lead to two soliton solutions u(x) = p(x) + iq(x) that also differ only by a sign. As the u(x)equation (6) is phase-invariant, solutions differing by a sign are equivalent. Thus, we will just take the plus sign for c_0 below. When c_0 is selected from the above formula (34), Equation (17) admits a localized solution for (p_1, q_1) , which we denote as (p_{1s}, q_{1s}) . However, since the kernel of the homogeneous operator \mathcal{L} in Equation (17) contains two localized functions K_1 and K_2 given in Equation (24), the general localized solution (p_1, q_1) to the linear nonhomogeneous equations (17) is then

$$\begin{bmatrix} p_1\\ q_1 \end{bmatrix} = \begin{bmatrix} p_{1s}\\ q_{1s} \end{bmatrix} + c_1 \begin{bmatrix} \phi\\ \psi \end{bmatrix} + d_1 \begin{bmatrix} -\psi\\ \phi \end{bmatrix}, \tag{35}$$

where c_1 and d_1 are two real constants.

It is important to recognize that the d_1 term above can be removed by phase invariance of the complex soliton solution u(x). To see this more clearly, we put the above perturbation solutions together and get

$$\begin{split} u(x) &= \epsilon^{1/2} \big[c_0 \phi + \epsilon (p_{1s} + c_1 \phi - d_1 \psi) + \mathbf{i} [c_0 \psi + \epsilon (\mathbf{q}_{1s} + c_1 \psi + d_1 \phi)] + \mathbf{O}(\epsilon^2) \big] \\ &= \epsilon^{1/2} \big[(c_0 + \epsilon c_1 + \mathbf{i} \epsilon \mathbf{d}_1) (\phi + \mathbf{i} \psi) + \epsilon (\mathbf{p}_{1s} + \mathbf{i} \mathbf{q}_{1s}) + \mathbf{O}(\epsilon^2) \big] \\ &= \epsilon^{1/2} e^{\mathbf{i} \epsilon \mathbf{d}_1 / c_0} \big[(c_0 + \epsilon c_1) (\phi + \mathbf{i} \psi) + \epsilon (\mathbf{p}_{1s} + \mathbf{i} \mathbf{q}_{1s}) + \mathbf{O}(\epsilon^2) \big]. \end{split}$$

Notice that the d_1 term only contributes a constant phase of order ϵ to the soliton solution u(x). But u(x) is phase-invariant. Thus, that d_1 term in (35) can be dropped and we can set

$$\begin{bmatrix} p_1 \\ q_1 \end{bmatrix} = \begin{bmatrix} p_{1s} \\ q_{1s} \end{bmatrix} + c_1 \begin{bmatrix} \phi \\ \psi \end{bmatrix}$$
(36)

without loss of generality.

The (p_1, q_1) solution in the above equation contains an unknown real constant c_1 . This c_1 constant will be determined from the Fredholm solvability condition on the (p_2, q_2) equations. The equations for (p_2, q_2) are (17), where the nonhomogeneous terms (f_2, g_2) are given in Equation (20). Substituting the (p_0, q_0) solutions (16) and (p_1, q_1) solutions (36) into the (f_2, g_2) expressions (20) and recalling that (ϕ, ψ) satisfy Equation (15), we find that the (f_2, g_2) expressions (20) reduce to

$$\begin{bmatrix} f_2 \\ g_2 \end{bmatrix} = \begin{bmatrix} f_{2a} \\ g_{2a} \end{bmatrix} + c_1 \begin{bmatrix} f_{2b} \\ g_{2b} \end{bmatrix},$$
(37)

where

$$\begin{split} f_{2a} &= (1 - 3\sigma p_0^2 - \sigma q_0^2) p_{1s} - 2\sigma p_0 q_0 q_{1s}, \\ f_{2b} &= (1 - 3\sigma p_0^2 - \sigma q_0^2) \phi - 2\sigma p_0 q_0 \psi, \\ g_{2a} &= \frac{1}{2c_0} \left[2(1 - \sigma p_0^2 - \sigma q_0^2) (p_0 p_{1s} + q_0 q_{1s}) + \mu_0 (p_{1s}^2 + q_{1s}^2) - (p_{1s,x} - g q_{1s})^2 - (q_{1s,x} + g p_{1s})^2 \right], \\ g_{2b} &= \frac{1}{c_0} \left[(1 - \sigma p_0^2 - \sigma q_0^2) (p_0 \phi + q_0 \psi) + \mu_0 (p_{1s} \phi + q_{1s} \psi) \right) \\ &- \left((p_{1s,x} - g q_{1s}) (\phi_x - g \psi) - (q_{1s,x} + g p_{1s}) (\psi_x + g \phi) \right], \end{split}$$

which are independent of the unknown constant c_1 . Then, the Fredholm solvability condition (30) at k = 2 gives the formula for the constant c_1 as

$$c_{1} = -\frac{\int_{-\infty}^{\infty} \left(\phi^{A} f_{2a} + \psi^{A} g_{2a}\right) dx}{\int_{-\infty}^{\infty} \left(\phi^{A} f_{2b} + \psi^{A} g_{2b}\right) dx}.$$
(38)

The rest of the perturbation calculations can then proceed to all orders as follows. When c_{k-1} $(k \ge 2)$ has been obtained, the (p_{k-1}, q_{k-1}) solutions are completely determined. Meanwhile, the solvability condition (30) for (p_k, q_k) is also satisfied, and thus, there exists a localized solution which we denote as $(p_{k,s}, q_{k,s})$. The general localized solutions for (p_k, q_k) can be written as

$$\begin{bmatrix} p_k \\ q_k \end{bmatrix} = \begin{bmatrix} p_{k,s} \\ q_{k,s} \end{bmatrix} + c_k \begin{bmatrix} \phi \\ \psi \end{bmatrix}.$$
(39)

The constant c_k will be determined from the solvability condition for the (p_{k+1}, q_{k+1}) equations (17). Specifically, when the above (p_k, q_k) solutions are inserted into the (f_{k+1}, g_{k+1}) formulas (21), it is easy to see that the solvability condition (30) at k + 1 is a linear equation for c_k , which we can easily solve to obtain the value of c_k as

$$c_{k} = -\frac{\left\langle \begin{bmatrix} \phi^{A} \\ \psi^{A} \end{bmatrix}, \begin{bmatrix} \mathcal{M}_{11} & \mathcal{M}_{12} \\ \mathcal{M}_{21} & \mathcal{M}_{22} \end{bmatrix} \begin{bmatrix} p_{k,s} \\ q_{k,s} \end{bmatrix} + \begin{bmatrix} \mathcal{N}_{k+1}^{[1]} \\ \mathcal{N}_{k+1}^{[2]} \end{bmatrix} \right\rangle}{\left\langle \begin{bmatrix} \phi^{A} \\ \psi^{A} \end{bmatrix}, \begin{bmatrix} \mathcal{M}_{11} & \mathcal{M}_{12} \\ \mathcal{M}_{21} & \mathcal{M}_{22} \end{bmatrix} \begin{bmatrix} \phi \\ \psi \end{bmatrix} \right\rangle}, \quad k \ge 2.$$

Utilizing the (p_1, q_1) formula (36) and the fact that (ϕ, ψ) satisfy Equation (15), we can verify that the denominator in this c_k formula is equal to the denominator in the c_1 formula (38). Thus, the above c_k formula can be reduced to

$$c_{k} = -\frac{\left\langle \begin{bmatrix} \phi^{A} \\ \psi^{A} \end{bmatrix}, \begin{bmatrix} \mathcal{M}_{11} & \mathcal{M}_{12} \\ \mathcal{M}_{21} & \mathcal{M}_{22} \end{bmatrix} \begin{bmatrix} p_{k,s} \\ q_{k,s} \end{bmatrix} + \begin{bmatrix} \mathcal{N}_{k+1}^{[1]} \\ \mathcal{N}_{k+1}^{[2]} \end{bmatrix} \right\rangle}{\int_{-\infty}^{\infty} (\phi^{A} f_{2b} + \psi^{A} g_{2b}) \, \mathrm{d}x}, \quad k \ge 2.$$

$$(40)$$

This process is then repeated to higher orders.

The only conditions for the above perturbation calculations to succeed to all orders are that the numerator and denominator in the c_0 formula (34), as well as the denominator in the c_1 formula (38), are all nonzero. Thus, we only have three numbers to check, which can be easily done for each given Equation (1) when its Wadati potential V(x) is specified.

2.5 | Comparison with numerics

In this subsection, we compare the above perturbation-series soliton solution (12)–(13) with the high-accuracy numerical solution, for a continuous range of small ϵ values, and confirm the asymptotic accuracy of this analytical solution.



FIGURE 1 Comparison of solitons between theory and numerics for the 1D equation (6) with $\sigma = 1$ and g(x) given by Equation (41). (A) Wadati potential (2), where solid blue is Re(*V*) and dashed red Im(*V*). (B) Linear eigenmode $\phi(x) + i\psi(x)$ of this potential, with solid blue being $\phi(x)$ and dashed red $\psi(x)$. (C) Localized adjoint eigenfunction, with solid blue being $\phi^A(x)$ and dashed red $\psi^A(x)$. (D) Amplitude profile $|u(x; \mu)|$ of the soliton at $\mu = \mu_0 + 0.1$, where solid blue is from numerical computation and red dots from analytical third-order perturbation series prediction. (E) Power curve of this soliton family, with solid blue from numerical computations and red dots from the third-order perturbation expansion (43). (F) Log-log plot of the power difference (45) between numerical values and the third-order perturbation expansion versus $\epsilon = \mu - \mu_0$. The dashed red line is the $\Delta P = \epsilon^4$ curve for comparison

In our comparison, we choose the non- \mathcal{PT} -symmetric Wadati potential (2) as the one with

$$g(x) = 0.8[\operatorname{sech}(x+2) + 1.2\operatorname{sech}(x-2)].$$
(41)

The resulting Wadati potential is shown in Figure 1A. This potential admits a discrete real eigenvalue $\mu_0 \approx 0.37080447$, and its corresponding eigenfunction $\phi(x) + i\psi(x)$ is plotted in Figure 1B. Numerically, we find that the adjoint operator \mathcal{L}^A in Equation (23) indeed admits a single localized function $(\phi^A, \psi^A)^T$ in its kernel, and this function is displayed in Figure 1C. Utilizing these eigenfunctions and adjoint eigenfunctions, the ratio of integrals under the square root in Equation (34) is found to be positive. Thus, according to our perturbation theory, a continuous family of solitons would bifurcate out for $\mu > \mu_0$ under the positive sign of nonlinearity $\sigma = 1$ and for $\mu < \mu_0$ under the negative sign of nonlinearity $\sigma = -1$.

Numerically, this is found to be the case. With the choice of positive sign of nonlinearity $\sigma = 1$, this soliton at $\mu = \mu_0 + 0.1$ is exhibited in Figure 1D. In addition, the power function of this soliton family, defined as

$$P(\mu) = \int_{-\infty}^{\infty} |u(x;\mu)|^2 \,\mathrm{d}x,$$
(42)

is shown in Figure 1E. These solitons are computed numerically by the Newton-conjugategradient method described in Ref. 18, and their numerical error is below 10^{-10} . Due to their high accuracy, we will call these numerical solutions as exact solutions in the remainder of this subsection.

Now, we make a more quantitative comparison between our perturbation-series solution and the exact solution. For this purpose, we first consider the perturbation-series solution (12)–(13) at $\mu = \mu_0 + 0.1$, that is, when $\epsilon = 0.1$. This analytical solution, to the third order of the perturbation series, is determined from the formulae and equations for (c_0, c_1, c_2) , (p_0, q_0) , (p_1, q_1) , and (p_2, q_2) in the previous subsection, and plotted in Figure 1D alongside the exact solution. As can be seen, this third-order perturbation solution is almost indistinguishable from the exact solution. This is not surprising, because this third-order perturbation solution has relative error of order ϵ^3 , or roughly 0.001 for $\epsilon = 0.1$, which is indeed very small.

Next, we compare the power function of our perturbation-series solutions (12)-(13) to that of the exact soliton solutions. For this purpose, we insert the perturbation-series solution (12)-(13) into the power function definition (42) and get

$$P_{anal}(\mu) = \epsilon P_1 + \epsilon^2 P_2 + \epsilon^3 P_3 + \cdots,$$
(43)

where $\mu = \mu_0 + \epsilon$ as before, and

$$P_1 = \int_{-\infty}^{\infty} (p_0^2 + q_0^2) dx, \quad P_2 = \int_{-\infty}^{\infty} 2(p_0 p_1 + q_0 q_1) dx, \quad P_3 = \int_{-\infty}^{\infty} \left[p_1^2 + q_1^2 + 2(p_0 p_2 + q_0 q_2) \right] dx$$

Using the (p_0, q_0) , (p_1, q_1) , and (p_2, q_2) solutions we have numerically obtained, we find that

$$P_1 \approx 5.89609348, \quad P_2 \approx -5.65066426, \quad P_3 \approx -9.38398099.$$
 (44)

Truncating the power-function expansion (43) to the third order, this truncated power function is plotted in Figure 1E alongside the exact power function. Again, the two functions are almost indistinguishable when μ is close to μ_0 .

The power series (43) is an asymptotic series. It does not have to be convergent, but it must satisfy the requirement of an asymptotic series, which is that $|P(\mu) - \sum_{k=1}^{n} \epsilon^k P_k| = o(\epsilon^n)$ when $\epsilon \to 0$ for every positive integer n.²⁹ To verify this asymptotic condition of our power series (43), we examine the difference between the third-order truncated power expansion (43) and the exact power function. According to our power expansion, this difference is expected to be

$$\Delta P \equiv P(\mu) - \epsilon P_1 - \epsilon^2 P_2 - \epsilon^3 P_3 = O(\epsilon^4).$$
⁽⁴⁵⁾

If this is indeed true, then the above asymptotic condition for n = 3 would be met. To confirm this $\Delta P = O(\epsilon^4)$ asymptotics for small ϵ , we show in Figure 1F a log-log plot of ΔP versus ϵ . Its comparison with the benchmark $\Delta P = \epsilon^4$ curve on the same graph shows that this ΔP is indeed $O(\epsilon^4)$ at small ϵ , confirming the asymptotic accuracy of our third-order power expansion.

In the above numerical example, we chose the focusing nonlinearity (with $\sigma = 1$). If the nonlinearity is defocusing, we have found similarly good agreement between perturbation-series solutions and the numerics.

2.6 | An alternative perturbation calculation

In the above perturbation calculation, we introduced the tangible small parameter as $\epsilon = \mu - \mu_0$. Because of that, we only needed to expand the solutions (p,q) into perturbation series. In this treatment, the $(p_n, q_n)^T$ solution at each order must contain the homogeneous term $c_n(\phi, \psi)^T$, so that c_n can be selected judiciously to satisfy the solvability condition of the linear nonhomogeneous $(p_{n+1}, q_{n+1})^T$ equation.

There is an alternative perturbation calculation, where we expand not only the solutions (p,q), but also the propagation constant μ , into perturbation series. In this treatment, the (p,q) expansion would still be (12)–(13), whereas the μ expansion would be

$$\mu = \mu_0 + \mu_1 \varepsilon + \mu_2 \varepsilon^2 + \cdots, \tag{46}$$

where μ_1, μ_2, \dots are real constants to be determined. Due to the introduction of these (μ_1, μ_2, \dots) parameters in the μ -expansion, we can choose each μ_n judiciously to satisfy the solvability condition of the linear nonhomogeneous $(p_n, q_n)^T$ equation. As a consequence, we do not need to introduce the homogeneous term $c_n(\phi, \psi)^T$ in the $(p_n, q_n)^T$ solution anymore. In this alternative treatment, we systematically detune the propagation constant μ ; although in the original treatment, we systematically detune the coefficient of the $(\phi, \psi)^T$ term in the $(p, q)^T$ solution, because that coefficient is $c_0 + c_1 \epsilon + c_2 \epsilon^2 + \cdots$. Algebrawise, this alternative perturbation calculation turns out to be a little simpler, because μ appears in the original two real soliton equations (9)–(10) in a simpler way than p and q, and thus, this μ -detuning introduces less terms in each (p_n, q_n) equation than our present treatment. The slight downside of this alternative treatment is that the "physical" meaning of the small parameter ϵ in it is less clear. Indeed, ϵ in this alternative treatment is more like a nontangible arbitrary book-keeping-type small parameter, to which both the propagation constant μ and the soliton solution (p,q) relate in a nontrivial parametric (perturbation-series) way. Overall, these two different perturbation procedures are roughly equivalent, and their choice is largely a personal taste. Indeed, we have also implemented this alternative perturbation treatment analytically and compared its results to the numerics, and found similar agreement as that shown in Figure 1.

3 | CONSTRUCTION OF SOLITON FAMILIES IN THE 2D CASE

Now, we consider the 2D NLS equation

$$iU_t + U_{xx} + U_{yy} + V(x, y)U + \sigma |U|^2 U = 0,$$
(47)

where V(x, y) is a complex potential and σ is the sign of nonlinearity. It has been shown in Ref. 16 that when this potential is of the form

$$V(x, y) = g^{2}(x) + ig'(x) + h(y),$$
(48)

where g(x) and h(y) are real functions, then its spectrum can be all-real. This potential is separable, and its *x*-part is the 1D Wadati potential (2). So, this 2D potential will also be called Wadati-type in this article. When g(x) is even, then this potential admits the partial \mathcal{PT} symmetry

 $V^*(x, y) = V(-x, y)$. In this case, Equation (47) admits continuous families of solitons, which has been demonstrated numerically and explained analytically in Ref. 30. However, when g(x) is not even, so that the potential V(x, y) is non- \mathcal{PT} -symmetric, numerical evidence in Ref. 18 indicates that Equation (47) could still admit continuous families of solitons, which is mysterious in the absence of \mathcal{PT} symmetry.

In this section, we analytically explain the existence of continuous families of solitons in the 2D NLS equation (47) with a non- \mathcal{PT} -symmetric Wadati-type potential (48) by extending the 1D perturbation calculations of the previous section to the present 2D case. In this potential (48), we require all of g(x), g'(x), and h(y) to be localized functions.

Solitons in Equation (47) are of the form

$$U(x, y, t) = e^{i\mu t} u(x, y),$$
 (49)

where μ is a real propagation constant, and u(x, y) is a localized function satisfying the 2D complex soliton equation

$$\left[\partial_{xx} + \partial_{yy} + g^2(x) + ig'(x) + h(y)\right]u - \mu u + \sigma |u|^2 u = 0.$$
(50)

3.1 | A real system for 2D solitons and its perturbation expansion

Similar to the 1D case, an important property of Equation (47) with the Wadati-type potential (48) is that it admits a conservation law even though it is non-Hamiltonian.¹⁸ Substituting the soliton solution (49) into that conservation law, we get a stationary real-valued flux equation

$$\frac{\partial J_1}{\partial x} + \frac{\partial J_2}{\partial y} = 0, \tag{51}$$

where

$$J_1 = |u_x + ig(x)u|^2 + [h(y) - \mu]|u|^2 + \frac{\sigma}{2}|u|^4 - |u_y|^2,$$
(52)

and

$$J_2 = u_x u_y^* + u_x^* u_y - ig(x)(u_y u^* - u u_y^*).$$
(53)

Following the 1D strategy, instead of working with the complex soliton equation (50), we will work with the real part of that soliton equation, that is,

$$\left[\partial_{xx} + \partial_{yy} + g^2(x) + h(y) - \mu\right] p - g'(x)q + \sigma(p^2 + q^2)p = 0,$$
(54)

where $u \equiv p + iq$ as before (see (8)), together with the real-valued flux equation (51), in our construction of a continuous family of 2D solitons. A minor difference from the 1D case is that here, we have to use the flux equation (51), which is the counterpart of the dJ/dx = 0 equation in the 1D case. This contrasts the 1D case where we used J = 0 directly. This minor difference in the starting equations for solitons will lead to minor differences in the technical constructions of soliton solutions, as we will see later in this section. The soliton family to be constructed bifurcates from a discrete real eigenvalue μ_0 of the potential. The corresponding localized eigenmode $\hat{\phi}(x, y) + i\hat{\psi}(x, y)$, with real $(\hat{\phi}, \hat{\psi})$, satisfies the linear eigenmode equation obtained by dropping the nonlinear term in the soliton equation (50), that is,

$$\left[\partial_{xx} + \partial_{yy} + g^2(x) + ig'(x) + h(y)\right](\hat{\phi} + i\hat{\psi}) = \mu_0(\hat{\phi} + i\hat{\psi}).$$
(55)

As the potential in this equation is separable, its linear mode is also separable and can be decomposed as

$$\hat{\phi}(x,y) = \phi(x)\zeta(y), \quad \hat{\psi}(x,y) = \psi(x)\zeta(y), \tag{56}$$

and $\mu_0 = \mu_{01} + \mu_{02}$, where $\phi(x) + i\psi(x)$ is a localized eigenmode of the *x*-part of the potential (a Wadati potential) with a discrete real eigenvalue μ_{01} , that is,

$$[\partial_{xx} + g^2(x) + ig'(x)](\phi + i\psi) = \mu_{01}(\phi + i\psi),$$
(57)

and $\zeta(y)$ is a real localized eigenmode of the *y*-part of the potential with a discrete real eigenvalue μ_{02} , that is,

$$\left[\partial_{yy} + h(y)\right]\zeta = \mu_{02}\zeta.$$
(58)

This 2D eigenmode $u = \hat{\phi}(x, y) + i\hat{\psi}(x, y)$ satisfies the flux equation (51) with the $|u|^4$ term dropped in J_1 and μ replaced by μ_0 .

Bifurcating from this linear eigenmode, we seek a low-amplitude soliton at each real propagation constant value μ near the linear eigenvalue μ_0 , and this soliton is expanded into the following perturbation series:

$$p(x, y; \mu) = \epsilon^{1/2} \left[p_0(x, y) + \epsilon p_1(x, y) + \epsilon^2 p_2(x, y) + \cdots \right],$$
(59)

$$q(x, y; \mu) = \epsilon^{1/2} \left[q_0(x, y) + \epsilon q_1(x, y) + \epsilon^2 q_2(x, y) + \cdots \right],$$
(60)

where $\epsilon = \mu - \mu_0$ and is assumed to be small positive (so that $\epsilon^{1/2}$ is real). As explained in the 1D case, this positive- ϵ assumption corresponds to a proper sign of nonlinearity σ , and the negative- ϵ case can be treated similarly.

Substituting the above perturbation expansion into Equations (51) and (54), we get a sequence of real equations for (p_k, q_k) . The equations for (p_0, q_0) are just the flux equation (51) with the $|u|^4$ term dropped in J_1 , and the linear part of Equation (54), with μ replaced by μ_0 . Their solutions are obviously

$$\begin{bmatrix} p_0 \\ q_0 \end{bmatrix} = c_0 \begin{bmatrix} \hat{\phi} \\ \hat{\psi} \end{bmatrix},$$
 (61)

where c_0 is a real constant to be determined. The equations for (p_k, q_k) $(k \ge 1)$ are the following linear nonhomogeneous system of equations:

$$\widehat{\mathcal{L}} \begin{bmatrix} p_k \\ q_k \end{bmatrix} = \begin{bmatrix} \hat{f}_k \\ \partial_x \hat{g}_{k1} + \partial_y \hat{g}_{k2} \end{bmatrix},$$
(62)

where $\hat{\mathcal{L}}$ is a 2 × 2 matrix operator whose elements are

$$\begin{split} &\hat{\mathcal{L}}_{11} = \partial_{xx} + \partial_{yy} + g^2 + h - \mu_0, \\ &\hat{\mathcal{L}}_{12} = -g_x, \\ &\hat{\mathcal{L}}_{21} = \partial_x \left[(\hat{\phi}_x - g\hat{\psi})\partial_x + g(\hat{\psi}_x + g\hat{\phi}) + (h - \mu_0)\hat{\phi} - \hat{\phi}_y \partial_y \right] + \partial_y \left[\hat{\phi}_y \partial_x + (\hat{\phi}_x - g\hat{\psi})\partial_y + g\hat{\psi}_y \right], \\ &\hat{\mathcal{L}}_{22} = \partial_x \left[(\hat{\psi}_x + g\hat{\phi})\partial_x - g(\hat{\phi}_x - g\hat{\psi}) + (h - \mu_0)\hat{\psi} - \hat{\psi}_y \partial_y \right] + \partial_y \left[\hat{\psi}_y \partial_x + (\hat{\psi}_x + g\hat{\phi})\partial_y - g\hat{\phi}_y \right], \end{split}$$

$$\begin{bmatrix} \hat{f}_1\\ \hat{g}_{11}\\ \hat{g}_{12} \end{bmatrix} = c_0 \begin{bmatrix} \hat{\phi} - \sigma c_0^2 (\hat{\phi}^2 + \hat{\psi}^2) \hat{\phi} \\ \frac{1}{2} (\hat{\phi}^2 + \hat{\psi}^2) - \frac{1}{4} \sigma c_0^2 (\hat{\phi}^2 + \hat{\psi}^2)^2 \\ 0 \end{bmatrix},$$
(63)

$$\begin{bmatrix} \hat{f}_{2} \\ \hat{g}_{21} \\ \hat{g}_{22} \end{bmatrix} = \begin{bmatrix} \left(1 - 3\sigma p_{0}^{2} - \sigma q_{0}^{2}\right) p_{1} - 2\sigma p_{0}q_{0}q_{1} \\ \frac{1}{2c_{0}} \left[2\left(1 - \sigma p_{0}^{2} - \sigma q_{0}^{2}\right) \left(p_{0}p_{1} + q_{0}q_{1}\right) + \left(\mu_{0} - h\right)\left(p_{1}^{2} + q_{1}^{2}\right)\right) \\ + \left(\left(p_{1y}^{2} + q_{1y}^{2}\right) - \left(p_{1x} - gq_{1}\right)^{2} - \left(q_{1x} + gp_{1}\right)^{2}\right] \\ - \frac{1}{c_{0}} \left[\left(p_{1x} - gq_{1}\right)p_{1y} + \left(q_{1x} + gp_{1}\right)q_{1y}\right] \end{bmatrix},$$
(64)

$$\begin{bmatrix} \hat{f}_k\\ \hat{g}_{k1}\\ \hat{g}_{k2} \end{bmatrix} = \begin{bmatrix} \widehat{\mathcal{M}}_{11} & \widehat{\mathcal{M}}_{12}\\ \widehat{\mathcal{M}}_{21} & \widehat{\mathcal{M}}_{22}\\ \widehat{\mathcal{M}}_{31} & \widehat{\mathcal{M}}_{32} \end{bmatrix} \begin{bmatrix} p_{k-1}\\ q_{k-1} \end{bmatrix} + \begin{bmatrix} \widehat{\mathcal{N}}_k^{[1]}\\ \widehat{\mathcal{N}}_k^{[2]}\\ \widehat{\mathcal{N}}_k^{[2]} \end{bmatrix}, \quad k \ge 3,$$
(65)

the matrix elements $\widehat{\mathcal{M}}_{ij}$ are k-independent and given by the formulas

$$\begin{split} \widehat{\mathcal{M}}_{11} &= 1 - 3\sigma p_0^2 - \sigma q_0^2, \\ \widehat{\mathcal{M}}_{12} &= -2\sigma p_0 q_0, \\ \widehat{\mathcal{M}}_{21} &= \frac{1}{c_0} \Big[p_0 \Big(1 - \sigma p_0^2 - \sigma q_0^2 \Big) + (\mu_0 - h) p_1 + p_{1y} \partial_y - (p_{1x} - gq_1) \partial_x - g(q_{1x} + gp_1) \Big], \\ \widehat{\mathcal{M}}_{22} &= \frac{1}{c_0} \Big[q_0 \Big(1 - \sigma p_0^2 - \sigma q_0^2 \Big) + (\mu_0 - h) q_1 + q_{1y} \partial_y + g(p_{1x} - gq_1) - (q_{1x} + gp_1) \partial_x \Big], \\ \widehat{\mathcal{M}}_{31} &= (p_{1x} - gq_1) \partial_y + p_{1y} \partial_x + gq_{1y}, \end{split}$$

$$\widehat{\mathcal{M}}_{32} = (q_{1x} + gp_1)\partial_y + q_{1y}\partial_x - gp_{1y},$$

and $\widehat{\mathcal{N}}_{k}^{[1]}, \widehat{\mathcal{N}}_{k}^{[2]}$ are functions that depend only on $k, p_0, p_1, \dots, p_{k-2}, q_0, q_1, \dots, q_{k-2}, g(x)$ and h(y).

3.2 | Kernel structures of the 2D linear operator and its adjoint operator

To solve the 2D linear nonhomogeneous equations (62) and obtain localized solutions (p_k, q_k) for all k, we will also use the Fredholm alternative method. To do so, we need to understand the kernel structures of the 2D operator $\hat{\mathcal{L}}$ and its adjoint operator $\hat{\mathcal{L}}^A$, where elements of the adjoint operator are

$$\begin{split} \hat{\mathcal{L}}_{11}^{A} &= \partial_{xx} + \partial_{yy} + g^{2} + h - \mu_{0}, \\ \hat{\mathcal{L}}_{21}^{A} &= -g_{x}, \\ \hat{\mathcal{L}}_{12}^{A} &= \left[\partial_{x}(\hat{\phi}_{x} - g\hat{\psi}) - g(\hat{\psi}_{x} + g\hat{\phi}) - (h - \mu_{0})\hat{\phi} - \partial_{y}\hat{\phi}_{y}\right]\partial_{x} + \left[\partial_{x}\hat{\phi}_{y} + \partial_{y}(\hat{\phi}_{x} - g\hat{\psi}) - g\hat{\psi}_{y}\right]\partial_{y}, \\ \hat{\mathcal{L}}_{22}^{A} &= \left[\partial_{x}(\hat{\psi}_{x} + g\hat{\phi}) + g(\hat{\phi}_{x} - g\hat{\psi}) - (h - \mu_{0})\hat{\psi} - \partial_{y}\hat{\psi}_{y}\right]\partial_{x} + \left[\partial_{x}\hat{\psi}_{y} + \partial_{y}(\hat{\psi}_{x} + g\hat{\phi}) + g\hat{\phi}_{y}\right]\partial_{y}. \end{split}$$

First, we consider the kernel structure of $\hat{\mathcal{L}}$. It is easy to check that this kernel contains two localized functions

$$\widehat{K}_1 \equiv \begin{bmatrix} \widehat{\phi} \\ \widehat{\psi} \end{bmatrix}, \quad \widehat{K}_2 \equiv \begin{bmatrix} -\widehat{\psi} \\ \widehat{\phi} \end{bmatrix}, \tag{66}$$

where

$$\widehat{\mathcal{L}}\widehat{K}_1 = \widehat{\mathcal{L}}\widehat{K}_2 = 0, \tag{67}$$

similar to the 1D case and for similar reasons. As the kernel equation $\hat{\mathcal{L}}\hat{K} = 0$ is the linearization of the two real "eigenvalue" equations for (p_0, q_0) (the 2D counterparts of 1D equations (14)–(15)) around the linear mode $(\hat{\phi}, \hat{\psi})$, localized functions in $\hat{\mathcal{L}}$'s kernel can only be induced by amplitude and phase invariances of these (p_0, q_0) equations, which result in \hat{K}_1 and \hat{K}_2 above. Thus, there are no other localized functions in $\hat{\mathcal{L}}$'s kernel.

Next, we consider the kernel structure of the adjoint 2D operator $\hat{\mathcal{L}}^A$. Due to the separability of the 2D eigenmode $(\hat{\phi}, \hat{\psi})$ in Equation (56), we can quickly verify that the kernel of $\hat{\mathcal{L}}^A$ contains a bounded function

$$\widehat{K}_{0}^{A} = \begin{bmatrix} \phi^{A}(x)\zeta(y) \\ -\int \psi^{A}(x)\mathrm{d}x \end{bmatrix},\tag{68}$$

where $\hat{\mathcal{L}}^A \hat{\mathcal{K}}_0^A = 0$, and $[\phi^A(x), \psi^A(x)]^T$ is the unique localized function (29) in the kernel of the 1D adjoint operator \mathcal{L}^A given in Equation (23), with μ_0 replaced by μ_{01} . One may notice that this kernel function of the 2D adjoint operator does not naturally fall back to the 1D adjoint kernel function (29). The reason is twofold. One is that the second column of the 2D adjoint operator $\hat{\mathcal{L}}^A$,

that is, $[\hat{\mathcal{L}}_{12}^A, \hat{\mathcal{L}}_{22}^A]^T$ given above, contains an additional spatial derivative compared to the second column of the 1D adjoint operator \mathcal{L}^A given in Equation (23)—a difference caused by our using the divergence form of the flux equation (51) in 2D instead of its integrated form J(x) = 0 in 1D. This difference in the second column of the adjoint operator explains the integral in the second element of \hat{K}_0^A above. The second reason for \hat{K}_0^A in 2D not naturally falling back to K_0^A in 1D is that the second columns of the two adjoint operators contain linear eigenmodes or their derivatives as multiplicative factors, whereas the first columns of these adjoint operators do not. Thus, in the 2D case, we need to introduce the factor $\zeta(y)$ from the 2D linear eigenmode (56) into the first element of the adjoint kernel function \hat{K}_0^A in Equation (68) in order to balance such a term coming from the second column of $\hat{\mathcal{L}}^A$.

We can further show that if h(y) is a slowly varying function, then the above \widehat{K}_0^A would be the only bounded function in the kernel of $\widehat{\mathcal{L}}^A$. To do so, let $h(y) = \widehat{\varepsilon}^2 H(Y)$ be a slowly varying function of $Y = \widehat{\varepsilon} y$, where $\widehat{\varepsilon}$ is a small real parameter. For this h(y), its eigenmode from Equation (58) is $\zeta(y) = \widehat{\zeta}(Y)$, with eigenvalue $\mu_{02} = O(\widehat{\varepsilon}^2)$. In this case, $\widehat{\mathcal{L}}^A$ can be rewritten as a quadratic function of $\widehat{\varepsilon}$,

$$\widehat{\mathcal{L}}^A = \widehat{\mathcal{L}}_0^A(x, Y) + \widehat{\varepsilon}\widehat{\mathcal{L}}_1^A(x, Y) + \widehat{\varepsilon}^2\widehat{\mathcal{L}}_2^A(x, Y),$$
(69)

where

$$\widehat{\mathcal{L}}_{0}^{A}(x,Y) = \begin{bmatrix} \partial_{xx} + g^{2} - \mu_{01} & \widehat{\zeta}(Y) [-\partial_{x}(\phi' - g\psi) + g(\psi' + g\phi) - \mu_{01}\phi](-\partial_{x}) \\ -g' & \widehat{\zeta}(Y) [-\partial_{x}(\psi' + g\phi) - g(\phi' - g\psi) - \mu_{01}\psi](-\partial_{x}) \end{bmatrix} \\
= \mathcal{L}^{A} \begin{bmatrix} 1 & 0 \\ 0 & -\widehat{\zeta}(Y)\partial_{x} \end{bmatrix},$$
(70)

and \mathcal{L}^A is the 1D adjoint operator (23) with μ_0 replaced by μ_{01} . As $\hat{\mathcal{L}}^A$ is a function of x, Y, and $\hat{\epsilon}$, functions \hat{F} in its kernel are also functions of these same variables and can be expanded into a perturbation series of $\hat{\epsilon}$ as

$$\widehat{F}(x,y;\widehat{\epsilon}) = \widehat{F}_0(x,Y) + \widehat{\epsilon}\widehat{F}_1(x,Y) + \widehat{\epsilon}^2\widehat{F}_2(x,Y) + \cdots.$$
(71)

Inserting this expansion and Equation (69) into $\hat{\mathcal{L}}^A \hat{F} = 0$ and using the kernel structures of the 1D operators \mathcal{L} and its adjoint \mathcal{L}^A detailed in Section 2.2, we can sequentially determine $\hat{F}_n(x, Y)$ in the above perturbation expansion and show that the only bounded function in the kernel of $\hat{\mathcal{L}}^A$ is

$$\widehat{F} = \begin{bmatrix} \phi^A(x)\widehat{\zeta}(Y) \\ -\int \psi^A(x)dx \end{bmatrix},\tag{72}$$

which matches (68) when the eigenmode $\zeta(y) = \hat{\zeta}(Y)$ is slowly varying. All other functions in the kernel of $\hat{\mathcal{L}}^A$ grow exponentially at large |x| or |Y|.

When h(y) continuously deforms from slowly varying to the general case of nonslowly varying, the above kernel structure of $\hat{\mathcal{L}}^A$ generically will not change, that is, its kernel will generically still contain a single bounded function (68). Although we cannot at this time rule out the possibility of additional bounded functions appearing in the kernel of $\hat{\mathcal{L}}^A$ at some special h(y) functions during this deformation process, for specific examples of the potentials, we can use numerics to directly verify this single-bounded-function kernel structure for $\hat{\mathcal{L}}^A$, so that our analysis below can proceed.

3.3 | Construction of perturbation series to all orders in 2D

With the above kernel structures of $\hat{\mathcal{L}}$ and $\hat{\mathcal{L}}^A$ in hand, we can now sequentially solve Equation (62) for localized solutions (p_k, q_k) using the Fredholm alternative method. According to this method, if functions $(\hat{f}_k, \hat{g}_{k1}, \hat{g}_{k2})$ on the right side of the linear nonhomogeneous system (62) are localized (which is the case here), this system would admit a localized solution (p_k, q_k) if and only if its right-hand side is orthogonal to the bounded function $\hat{\mathcal{K}}_0^A$ of (68) in the kernel of $\hat{\mathcal{L}}^A$, that is,

$$\left\langle \begin{bmatrix} \phi^A(x)\zeta(y) \\ -\int \psi^A(x)dx \end{bmatrix}, \begin{bmatrix} \hat{f}_k \\ \hat{\partial}_x \hat{g}_{k1} + \hat{\partial}_y \hat{g}_{k2} \end{bmatrix} \right\rangle = 0.$$
(73)

It is noted that the arbitrary constant out of the indefinite integral $\int \psi^A(x) dx$ gives no contribution to the inner product in the above solvability condition. In addition, the above integral is convergent because $(\hat{f}_k, \hat{g}_{k1}, \hat{g}_{k2})$ are all localized in space.

Our perturbative construction of 2D solitons bifurcating from a linear localized eigenmode of the complex potential (48) proceeds similarly as the 1D case, because the kernel structures in the 2D case resemble those in the 1D case. We first consider Equation (62) for (p_1, q_1) . Substituting the $(\hat{f}_1, \hat{g}_{11}, \hat{g}_{12})$ expressions (63) into the above solvability condition and performing integration by parts, we get

$$\left\langle \begin{bmatrix} \phi^A(x)\zeta(y)\\ \psi^A(x) \end{bmatrix}, \begin{bmatrix} \hat{f}_1\\ \hat{g}_{11} \end{bmatrix} \right\rangle = 0.$$
(74)

Inserting the $(\hat{f}_1, \hat{g}_{11})$ expressions (63) and $(\hat{\phi}, \hat{\psi})$ formulas (56) into the above equation, we obtain a formula for c_0 as

$$c_{0} = \pm \sqrt{\frac{\int_{-\infty}^{\infty} \left[\phi \phi^{A} + \frac{1}{2}(\phi^{2} + \psi^{2})\psi^{A}\right] dx}{\sigma \int_{-\infty}^{\infty} \left[(\phi^{2} + \psi^{2})\phi \phi^{A} + \frac{1}{4}(\phi^{2} + \psi^{2})^{2}\psi^{A}\right] dx} \frac{\int_{-\infty}^{\infty} \zeta^{2}(y) dy}{\int_{-\infty}^{\infty} \zeta^{4}(y) dy}}.$$
 (75)

As in the 1D case, the sign of σ must match the sign of the ratio between integrals in the above equation so that the quantity under the square root is positive. In addition, we can choose the plus sign outside the square root without loss of generality.

When c_0 is selected from the above formula (75), Equation (62) admits a localized solution for (p_1, q_1) , which we denote as (p_{1s}, q_{1s}) . Since the kernel of the homogeneous operator $\hat{\mathcal{L}}$ in Equation (62) contains two localized functions \hat{K}_1 and \hat{K}_2 given in Equation (66), the general localized solution (p_1, q_1) to the linear nonhomogeneous equations (62) is then $[p_{1s}, q_{1s}]^T + c_1\hat{K}_1 + d_1\hat{K}_2$, where c_1 and d_1 are two real constants. But as in the 1D case, the d_1 term can be removed by phase

invariance of the complex soliton solution u(x, y). Thus, the (p_1, q_1) solution can be set as

$$\begin{bmatrix} p_1\\ q_1 \end{bmatrix} = \begin{bmatrix} p_{1s}\\ q_{1s} \end{bmatrix} + c_1 \begin{bmatrix} \hat{\phi}\\ \hat{\psi} \end{bmatrix}.$$
(76)

The constant c_1 in this solution will be determined from the Fredholm solvability condition on the (p_2, q_2) equations.

The equations for (p_2, q_2) are (62), where $(\hat{f}_2, \hat{g}_{21}, \hat{g}_{22})$ in the nonhomogeneous terms are given in Equation (64). Substituting the (p_0, q_0) solutions (61) and (p_1, q_1) solutions (76) into these nonhomogeneous terms and recalling that the eigenmode $u = \hat{\phi}(x, y) + i\hat{\psi}(x, y)$ satisfies the flux equation (51) with the $|u|^4$ term dropped in J_1 and μ replaced by μ_0 , we see that the right side of Equation (62) for (p_2, q_2) reduces to

$$\begin{bmatrix} \hat{f}_2\\ \partial_x \hat{g}_{21} + \partial_y \hat{g}_{22} \end{bmatrix} = \begin{bmatrix} \hat{f}_{2a}\\ \partial_x \hat{g}_{21a} + \partial_y \hat{g}_{22a} \end{bmatrix} + c_1 \begin{bmatrix} \hat{f}_{2b}\\ \partial_x \hat{g}_{21b} + \partial_y \hat{g}_{22b} \end{bmatrix},$$
(77)

where

$$\begin{split} \hat{f}_{2a} &= \left(1 - 3\sigma p_0^2 - \sigma q_0^2\right) p_{1s} - 2\sigma p_0 q_0 q_{1s}, \\ \hat{g}_{21a} &= \frac{1}{2c_0} \left[2 \left(1 - \sigma p_0^2 - \sigma q_0^2\right) (p_0 p_{1s} + q_0 q_{1s}) + (\mu_0 - h)(p_{1s}^2 + q_{1s}^2) + (p_{1s,y}^2 + q_{1s,y}^2) \right) \\ &- \left((p_{1s,x} - g q_{1s})^2 - (q_{1s,x} + g p_{1s})^2) \right], \\ \hat{g}_{22a} &= -\frac{1}{c_0} \left[(p_{1s,x} - g q_{1s}) p_{1s,y} + (q_{1s,x} + g p_{1s}) q_{1s,y} \right], \end{split}$$

and

$$\begin{split} \hat{f}_{2b} &= (1 - 3\sigma p_0^2 - \sigma q_0^2) \hat{\phi} - 2\sigma p_0 q_0 \hat{\psi}, \\ \hat{g}_{21b} &= \frac{1}{c_0} \left[\left(1 - \sigma p_0^2 - \sigma q_0^2 \right) (p_0 \hat{\phi} + q_0 \hat{\psi}) + (\mu_0 - h) (p_{1s} \hat{\phi} + q_{1s} \hat{\psi}) + (p_{1s,y} \hat{\phi}_y + q_{1s,y} \hat{\psi}_y) \right) \\ &- \left((p_{1s,x} - g q_{1s}) (\hat{\phi}_x - g \hat{\psi}) - (q_{1s,x} + g p_{1s}) (\hat{\psi}_x + g \hat{\phi}) \right], \\ \hat{g}_{22b} &= -\frac{1}{c_0} \left[(p_{1s,x} - g q_{1s}) \hat{\phi}_y + p_{1s,y} (\hat{\phi}_x - g \hat{\psi}) + (q_{1s,x} + g p_{1s}) \hat{\psi}_y + q_{1s,y} (\hat{\psi}_x + g \hat{\phi}) \right]. \end{split}$$

Inserting (77) into the Fredholm solvability condition (73) at k = 2, we get a formula for the constant c_1 as

$$c_{1} = -\frac{\left\langle \begin{bmatrix} \phi^{A}(x)\zeta(y) \\ -\int \psi^{A}(x)dx \end{bmatrix}, \begin{bmatrix} \hat{f}_{2a} \\ \partial_{x}\hat{g}_{21a} + \partial_{y}\hat{g}_{22a} \end{bmatrix} \right\rangle}{\left\langle \begin{bmatrix} \phi^{A}(x)\zeta(y) \\ -\int \psi^{A}(x)dx \end{bmatrix}, \begin{bmatrix} \hat{f}_{2b} \\ \partial_{x}\hat{g}_{21b} + \partial_{y}\hat{g}_{22b} \end{bmatrix} \right\rangle}.$$
(78)

When the c_1 value is selected as above, the (p_1, q_1) solutions (76) are completely determined. In addition, the Fredholm solvability condition (73) for the (p_2, q_2) equations (62) is also satisfied; so these equations admit a localized (p_2, q_2) solution, which we denote as (p_{2s}, q_{2s}) . In view of the kernel structure of operator $\hat{\mathcal{L}}$ and phase invariance of the complex soliton solution u(x, y), the general localized solutions for (p_2, q_2) can be written as

$$\begin{bmatrix} p_2 \\ q_2 \end{bmatrix} = \begin{bmatrix} p_{2s} \\ q_{2s} \end{bmatrix} + c_2 \begin{bmatrix} \hat{\phi} \\ \hat{\psi} \end{bmatrix},$$
(79)

where c_2 is a real constant. This constant c_2 will be determined from the Fredholm solvability condition for the (p_3, q_3) equations. Indeed, inserting this (p_2, q_2) solution into the right side of Equation (62) with k = 3, it is easy to see that the solvability condition (73) at k = 3 is a linear equation for c_2 , which we can easily solve to obtain the value of c_2 . After this c_2 value is obtained, (p_2, q_2) is ascertained. In addition, the (p_3, q_3) equation admits a localized solution, which we denote as (p_{3s}, q_{3s}) , and the general (p_3, q_3) solutions can be written as (79) with the index changed from 2 to 3. This process is then repeated to higher orders.

3.4 | Comparison with numerics in 2D

Lastly, we compare the above 2D perturbation series soliton solution (59)-(60) with the highaccuracy numerical solution and confirm the asymptotic accuracy of this 2D analytical solution. In our comparison, we choose the potential (48) with

$$g(x) = 0.8[\operatorname{sech}(x+2) + 1.2\operatorname{sech}(x-2)], \quad h(y) = 2\operatorname{sech}^2 y.$$
(80)

Notice that this g(x) function is the same as (41) in the 1D example. This potential admits a discrete real eigenvalue $\mu_0 = \mu_{01} + \mu_{02} \approx 1.37080447$, where $\mu_{01} \approx 0.37080447$ as in the 1D case, and $\mu_{02} = 1$. The corresponding eigenfunction $(\hat{\phi}, \hat{\psi})$ is given in Equation (56), where $[\phi(x), \psi(x)]$ is as shown in Figure 1B, and $\zeta(y) = \operatorname{sech}(y)$. Numerically, we confirmed that the 2D adjoint operator $\hat{\mathcal{L}}^A$ indeed admits a single bounded function (68) in its kernel, where $[\phi^A(x), \psi^A(x)]$ is the localized function (29) in the kernel of the 1D adjoint operator \mathcal{L}^A in Equation (23), which was plotted in Figure 2C.

When $\sigma = 1$ (focusing nonlinearity), our theory predicts that a continuous family of solitons bifurcates out from the above linear discrete eigenmode when $\mu > \mu_0$. This is indeed the case. For the choice of $\mu = \mu_0 + 0.1$ (i.e., $\epsilon = 0.1$), the second-order perturbation-series solution (59)– (60) is determined from the formulas and equations for c_0, c_1, p_0, q_0, p_1 , and q_1 in the previous subsection, and plotted in Figure 2A. The high-accuracy numerical solution at this same μ value is displayed in Figure 2B for comparison. It is seen that these two solutions are visually identical. We have also calculated the difference between these two solutions, and found that the relative error between them is under 2.5%, which is $O(\epsilon^2)$ (i.e., order of 0.01) as expected.

Next, we compare the power function of our perturbation-series solutions (59)–(60) to that of the exact soliton solutions. This 2D power function is defined as

$$P(\mu) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} |u(x, y; \mu)|^2 \, \mathrm{d}x \mathrm{d}y, \tag{81}$$



FIGURE 2 Comparison of solitons between theory and numerics for the 2D equation (50) with $\sigma = 1$, and g(x), h(y) given by Equation (80). (a) Amplitude profile $|u(x, y; \mu)|$ of the second-order perturbation series solution (82) at $\mu = \mu_0 + 0.1$. (b) Numerically computed soliton |u| at the same μ value of (A). (c) Power curve of this soliton family, with solid blue from numerical computations and red dots from the second-order perturbation expansion (82). (d) Log-log plot of the power difference between numerical values and the second-order perturbation expansion versus $\epsilon = \mu - \mu_0$. Dashed red line is the $\Delta P = \epsilon^3$ curve for comparison

analogous to the 1D case (42). Inserting the perturbation-series solution (59)-(-60) into this power function, we get

$$P_{anal}(\mu) = \epsilon P_1 + \epsilon^2 P_2 + \cdots,$$
(82)

where

$$P_1 = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (p_0^2 + q_0^2) dx dy, \quad P_2 = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} 2(p_0 p_1 + q_0 q_1) dx dy.$$
(83)

Using the (p_0, q_0) and (p_1, q_1) solutions obtained from Equations (61) and (76), we find that

$$P_1 \approx 17.68828045, P_2 \approx -21.74575.$$

Truncating the power-function expansion (82) to these first two terms, this truncated power function is plotted in Figure 2C alongside the exact power function. Again, the two functions are almost indistinguishable. To verify the asymptotic accuracy of our perturbation series solutions, we show in Figure 2D a log-log plot of $\Delta P \equiv \epsilon P_1 + \epsilon^2 P_2 - P(\mu)$ versus ϵ . Its comparison with the benchmark $\Delta P = \epsilon^3$ curve on the same graph shows that this ΔP is $O(\epsilon^3)$, which matches our asymptotic prediction for this quantity. The above comparison indicates that the true 2D soliton solutions and our perturbation series solutions are in perfect agreement.

4 | SUMMARY AND DISCUSSION

In this article, we have analytically constructed continuous families of low-amplitude solitons bifurcating from linear modes in one- and two-dimensional NLS equations with localized Wadatitype non- \mathcal{PT} -symmetric complex potentials, thus providing an analytical explanation for this counterintuitive phenomenon of soliton families appearing in these non- \mathcal{PT} -symmetric non-Hamiltonian systems. Our analytical construction utilized the conservation laws of these non- \mathcal{PT} -symmetric equations, which allowed us to convert the complex soliton equations into new real systems. A key advantage of these new real systems is that, during a perturbation expansion of low-amplitude solitons bifurcating from linear modes, the underlying linear operator has two localized functions in its kernel, and the associated adjoint operator has a single localized or bounded function in its kernel. This kernel structure, coupled with the phase invariance of the complex soliton, guarantees that at each order of the soliton's perturbation expansion, the Fredholm solvability condition can always be satisfied, so that a localized solution at each order of the perturbation series can be found. As a result, a continuous family of low-amplitude solitons bifurcating from a linear mode is obtained as a perturbation series to all orders of the small soliton amplitude. We have also compared these analytically constructed soliton solutions to highaccuracy numerical solutions, in both one and two spatial dimensions, and the asymptotic accuracy of these perturbation solutions is fully confirmed.

In this article, the nonlinearity in our 1D and 2D NLS equations (1) and (47) is cubic. But our analytical treatment for this cubic nonlinearity can be trivially generalized to other types of non-linearities of the general form $G(|U|^2)U$, where $G(\cdot)$ is an arbitrary real function. Indeed, for the 1D and 2D NLS equations (1) and (47) with this more general form of nonlinearity but the same Wadati-type complex potentials (2) and (48), a conservation law still exists.^{18,19} Thus, the analytical treatment of this article still applies.

In our perturbative construction of soliton families in the NLS equations (1) and (47) with non- \mathcal{PT} -symmetric Wadati-type potentials, the conservation laws of those equations played a critical role. If such conservation laws are absent, such as for non- \mathcal{PT} -symmetric complex potentials not of Wadati-type, this construction would not work. In such cases, we do not believe that true soliton families can still exist. This implies that we do not think that the "soliton families" reported in Ref. 25 for non-Wadati complex potentials are true soliton solutions.

A closely related subject is symmetry breaking of solitons in \mathcal{PT} -symmetric Wadati-type potentials (2) and (48), where g(x) is an even function. It is known that for generic \mathcal{PT} -symmetric potentials, symmetry breaking of solitons is forbidden. However, for \mathcal{PT} -symmetric Wadati-type potentials (2) and (48), symmetry breaking of solitons can occur, where two branches of non- \mathcal{PT} symmetric solitons bifurcate out from the base branch of \mathcal{PT} -symmetric solitons when the base branch's power reaches a certain threshold.^{18,31} So far, there has been no analytical explanation for these symmetry breakings. For \mathcal{PT} -symmetric Wadati-type potentials, the conservation laws (3) and (51) are still valid. Then, using our new real system of soliton equations in this article, together with bifurcation conditions for symmetry breaking, branches of symmetric and asymmetric solitons in these \mathcal{PT} -symmetric Wadati-type potentials could be perturbatively constructed near the symmetry-breaking point. Details of this construction will be left for future studies.

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DATA AVAILABILITY STATEMENT

The data that support the findings of this study are available from the corresponding author upon reasonable request.

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